

Mobile Matrix

A Multihop Address Allocation and Any-To-Any Routing in Mobile 6LoWPAN

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Agenda

1. Introduction and Motivation
2. Design Overview
3. Handling Mobility
4. Complexity Analysis
5. Experiments
6. Related Works
7. Conclusions and Future Work

1.

Introduction and Motivation

Routing under
mobility scenario

Introduction and Motivation

- ▣ Mobility is a major factor present in everyday life
 - ▣ It makes life easier and applications more flexible
 - ▣ IoT can benefit from it
- ▣ Routing and addressing standards for low-power devices (RPL, CTP, 6LoWPAN/IPv6)
 - ▣ They do not handle **mobility**
- ▣ Routing under mobility scenario trade-offs
 - ▣ Memory
 - ▣ Control messages
 - ▣ Routing rules complexity

Introduction and Motivation

- Mobile Matrix (μ Matrix)
 - Routing protocol for 6LoWPAN
 - Any-to-any routing enabled
 - It uses hierarchical address allocation
 - It enhances memory resource usage
 - Node Mobility Management
 - Nodes do not ever change its IPv6 address

Mobile Matrix (μ Matrix)



1. Low routing memory footprint
2. Adjustable control message overhead
3. Routing under mobility without changing nodes IPv6 Address

2.

Design overview

1. Architecture
2. Hierarchical Address allocation
3. Mobility management

Design Overview

μMatrix Architecture



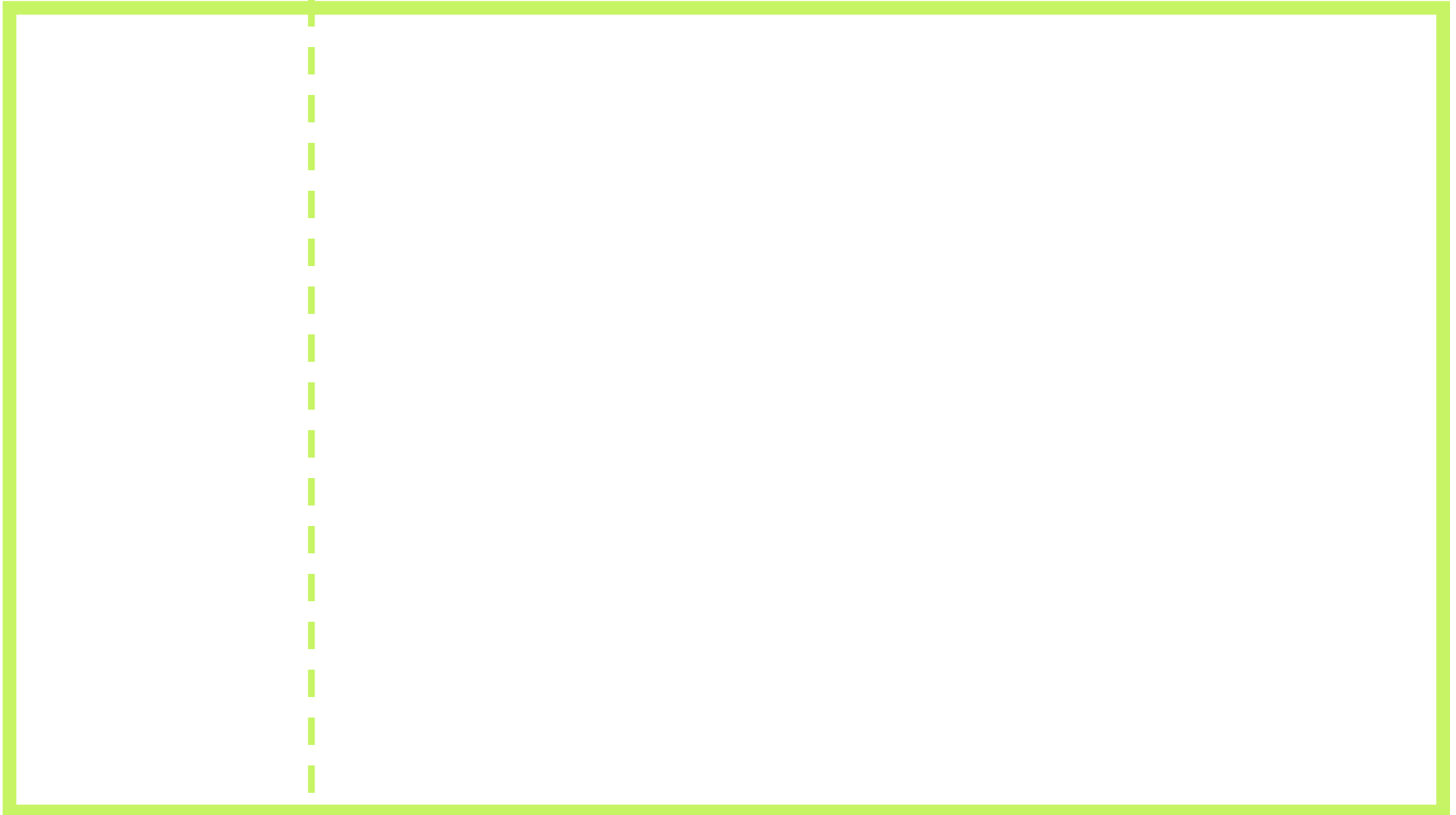
Design Overview

μMatrix Architecture



Data Plane

Control Plane

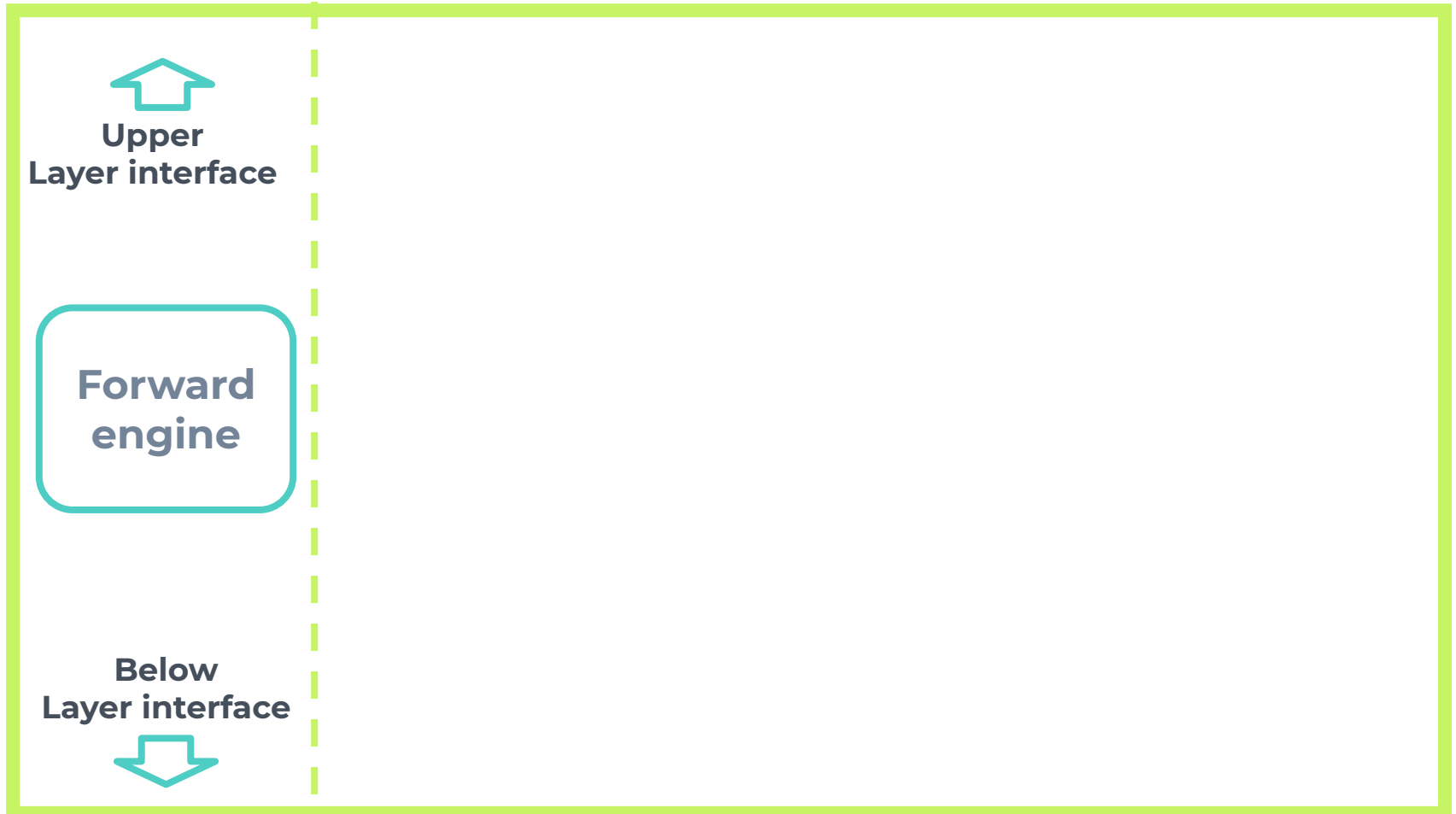


Design Overview

μMatrix Architecture

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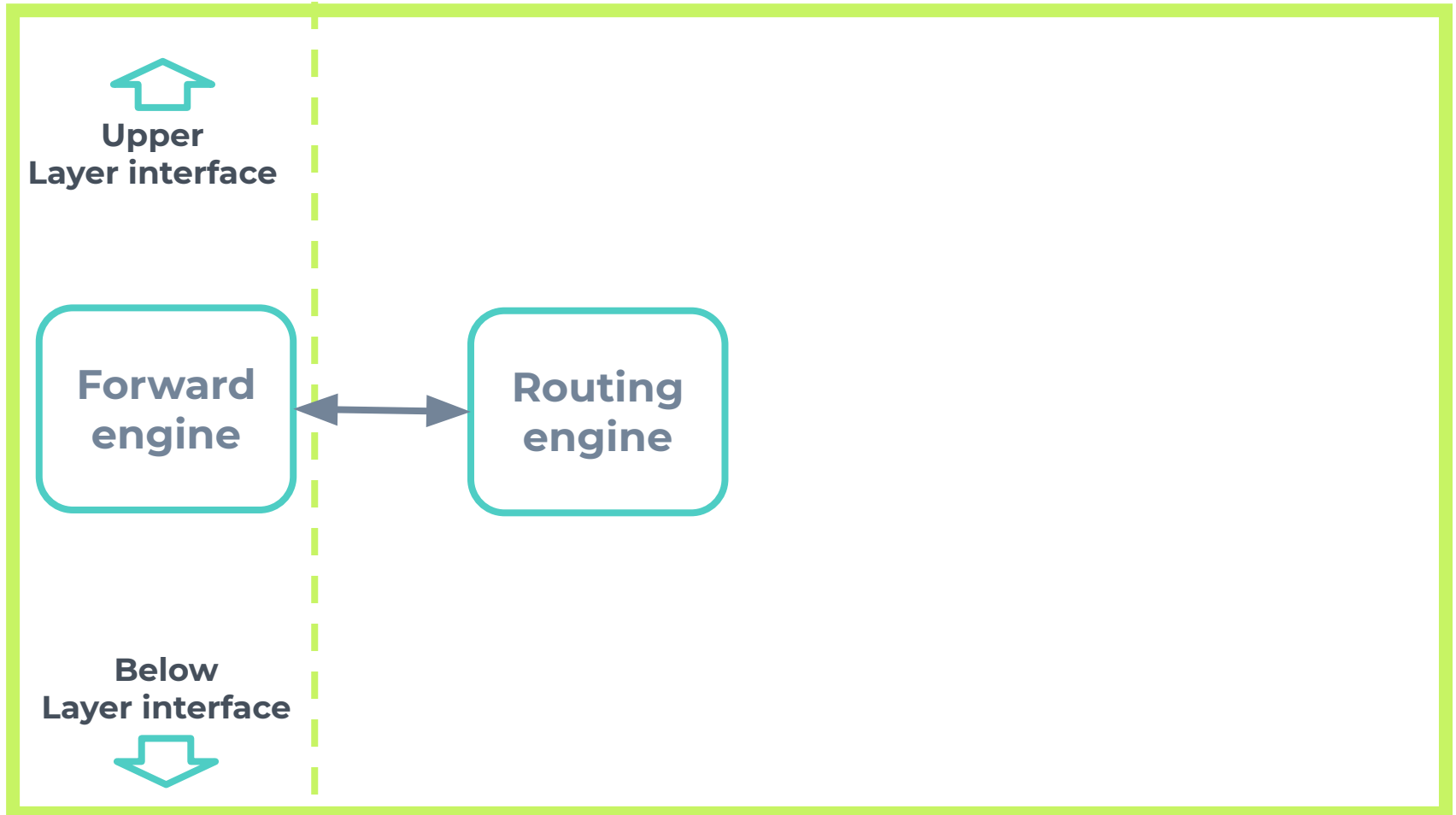


Design Overview

μMatrix Architecture

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Control Plane

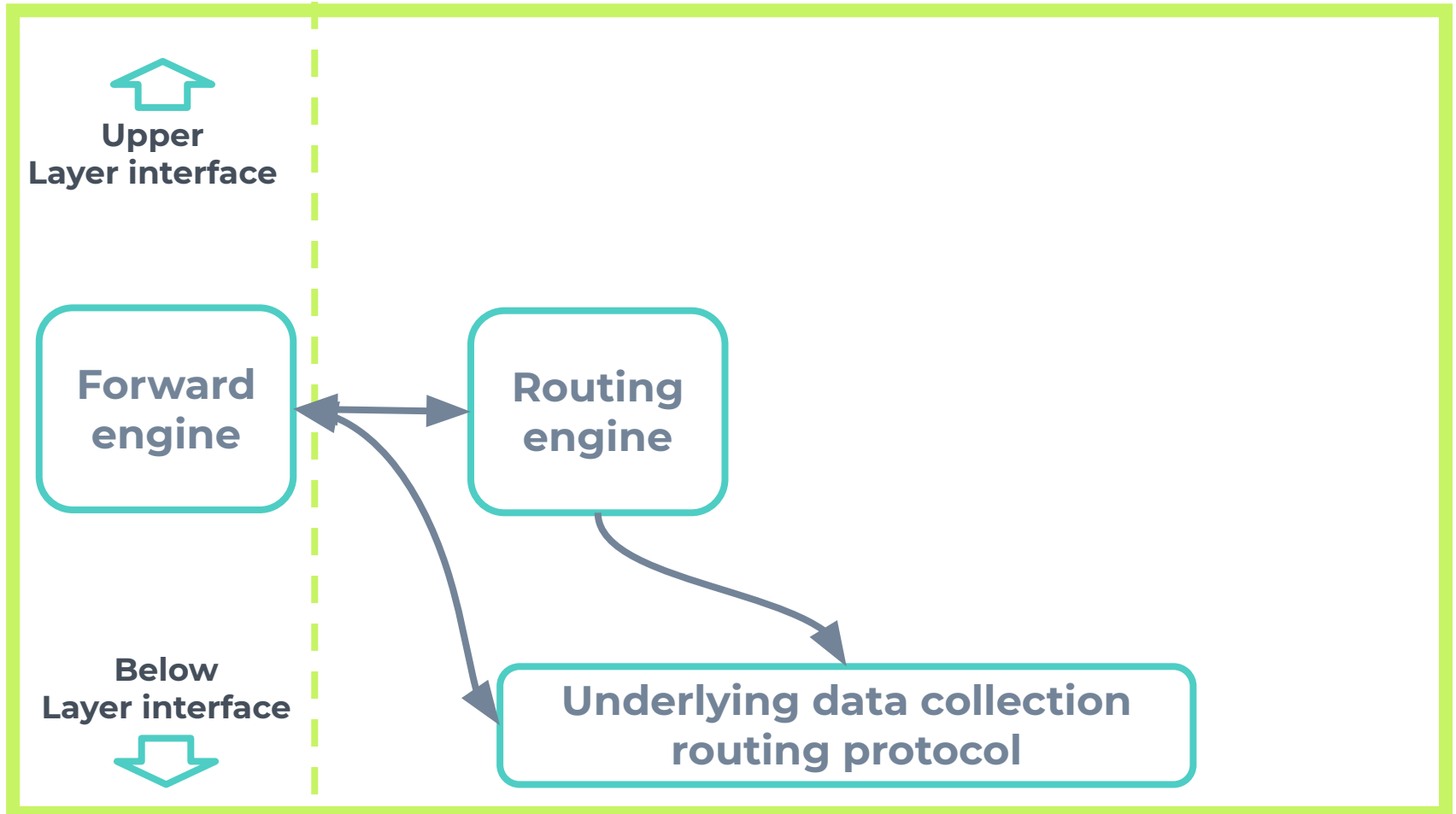


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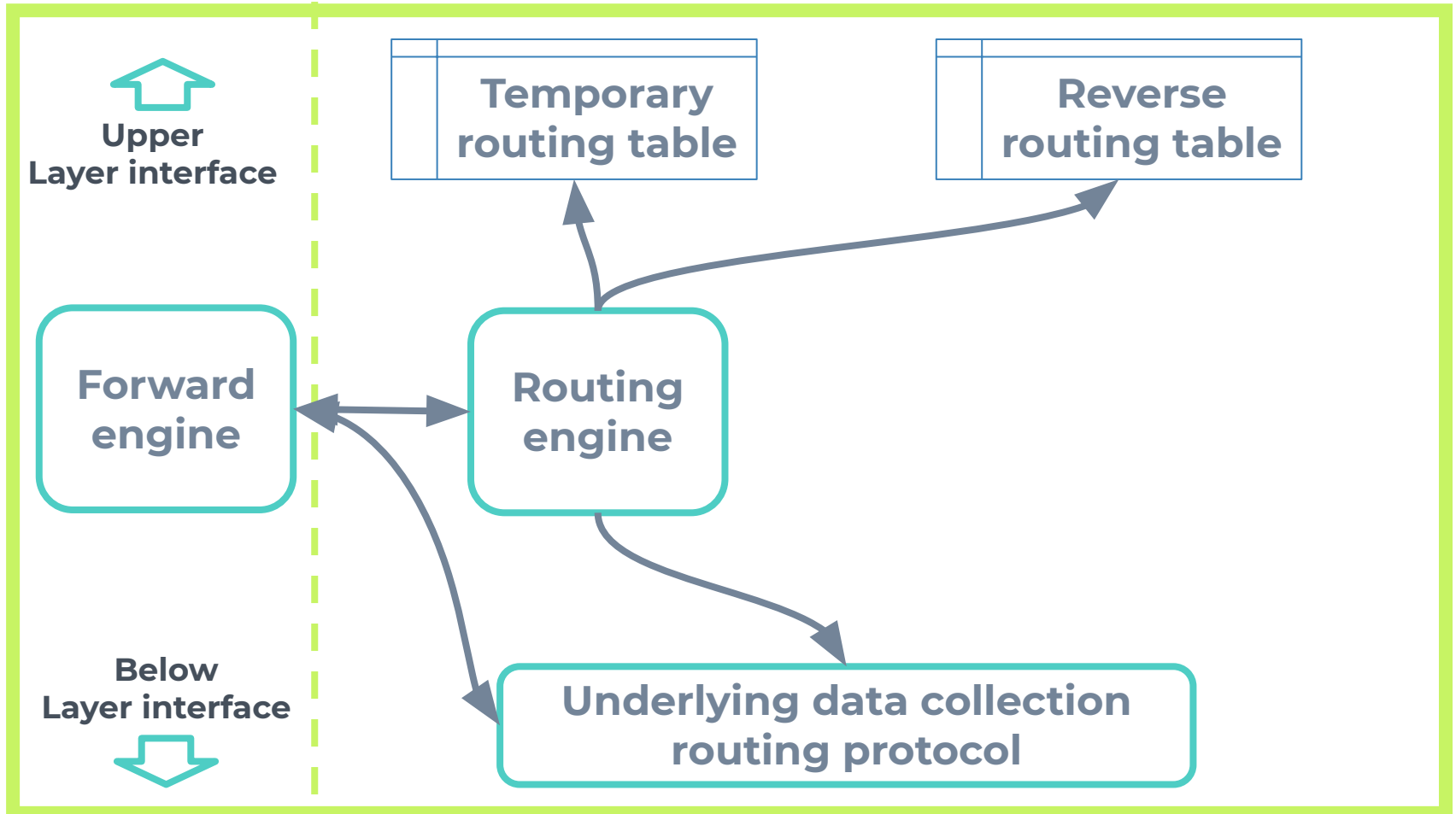


Design Overview

μMatrix Architecture

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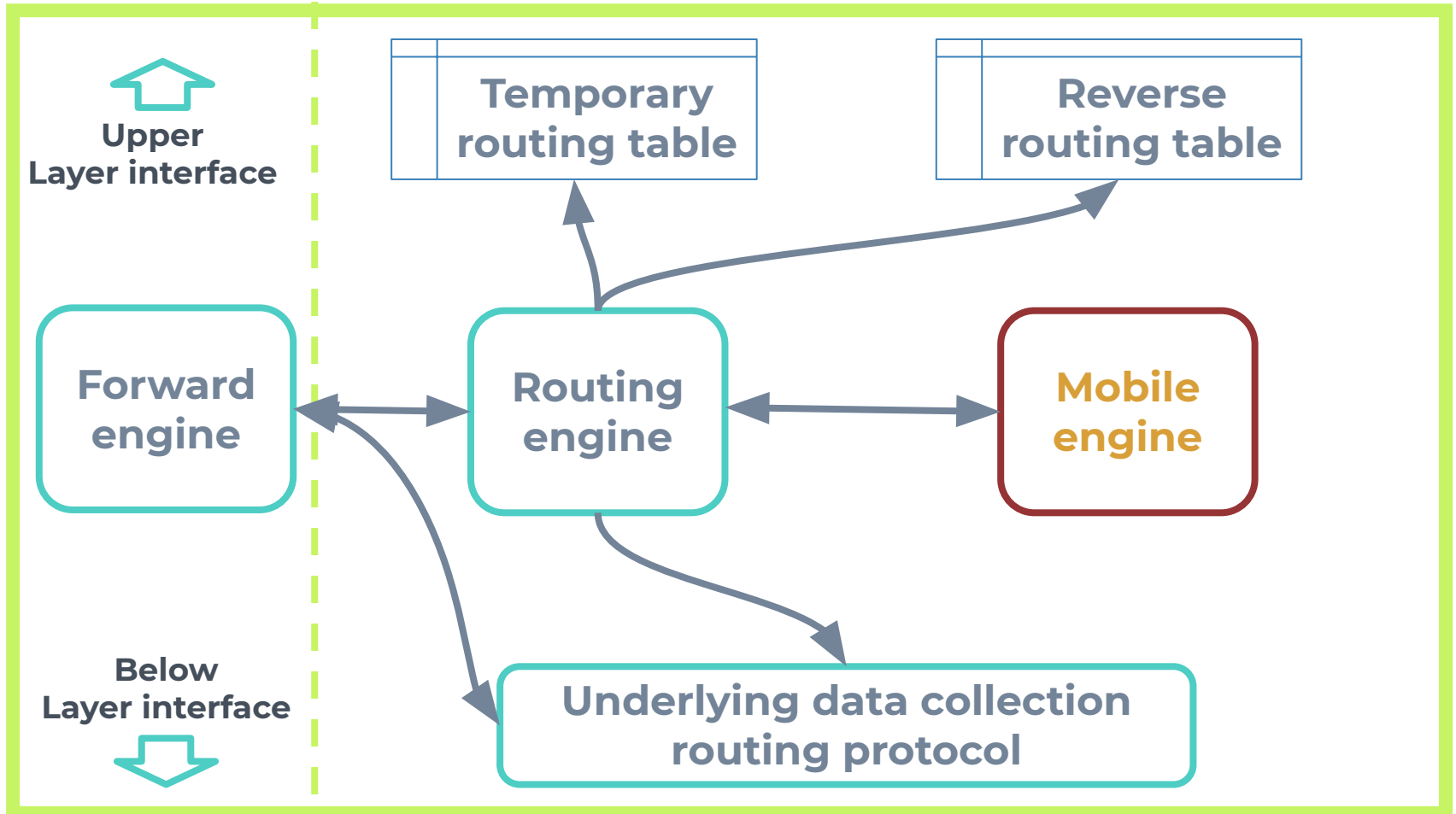


Design Overview

μMatrix Architecture

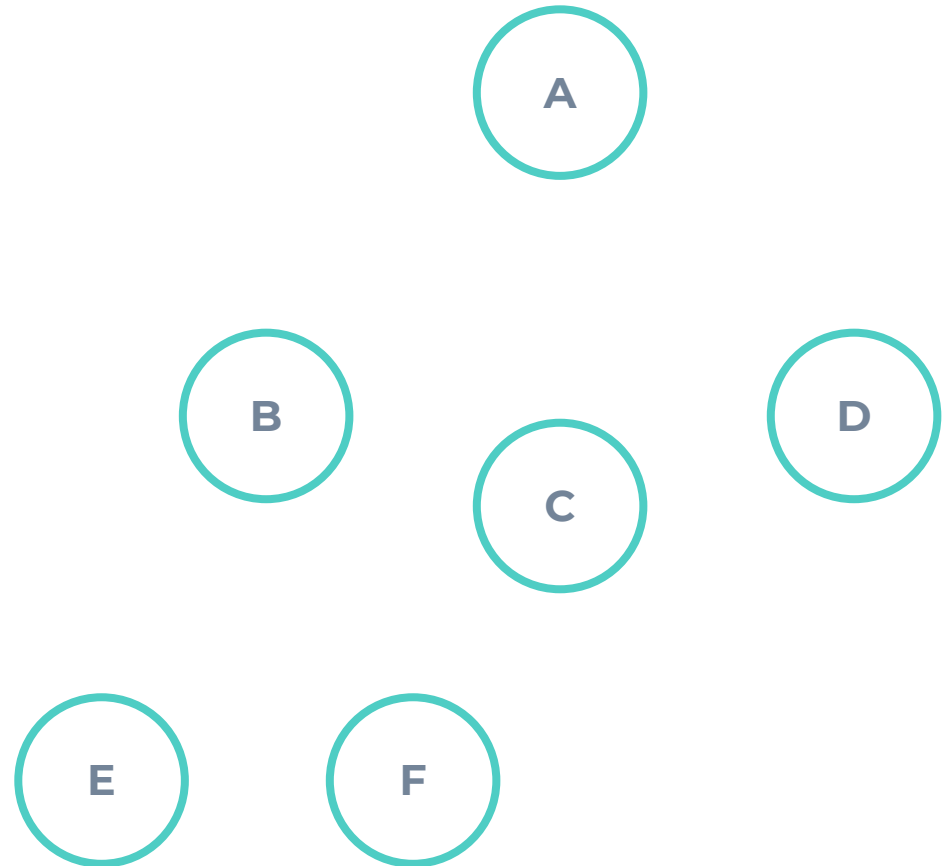
Data Plane

Control Plane



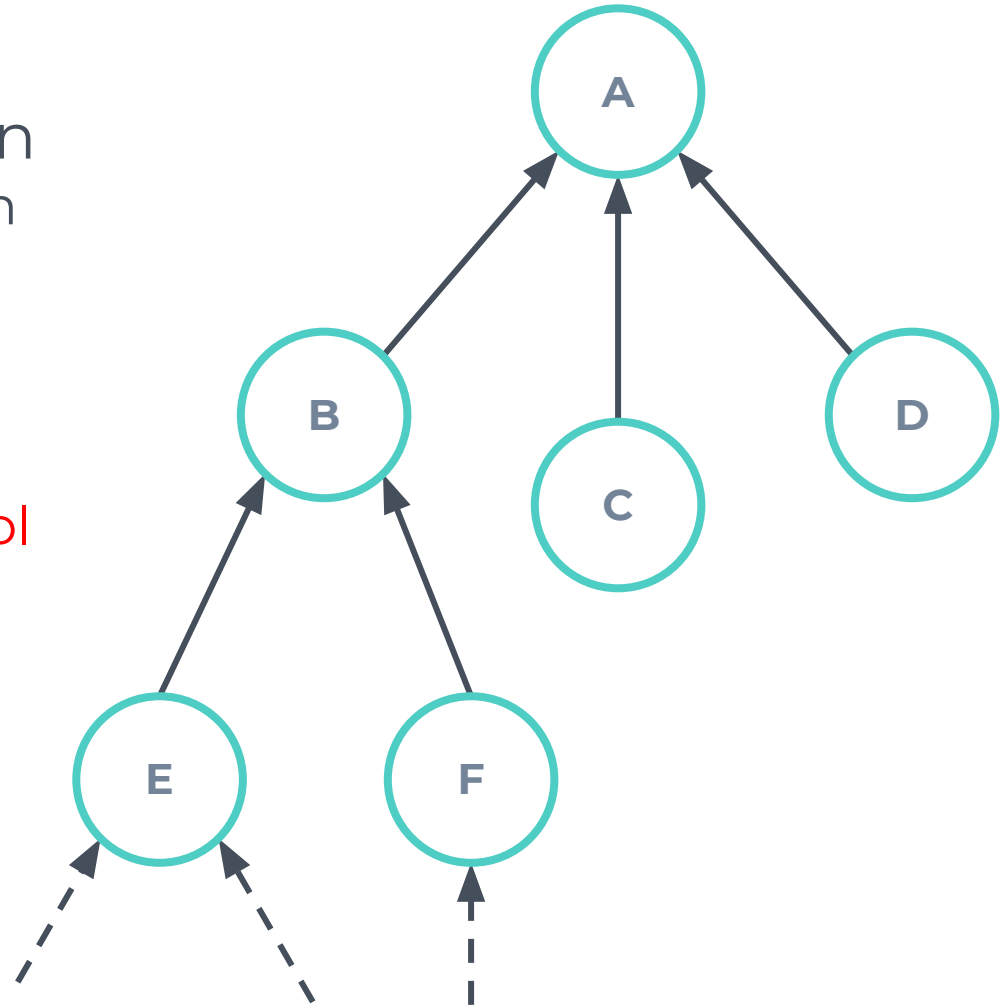
Design Overview

μMatrix Hierarchical Address allocation



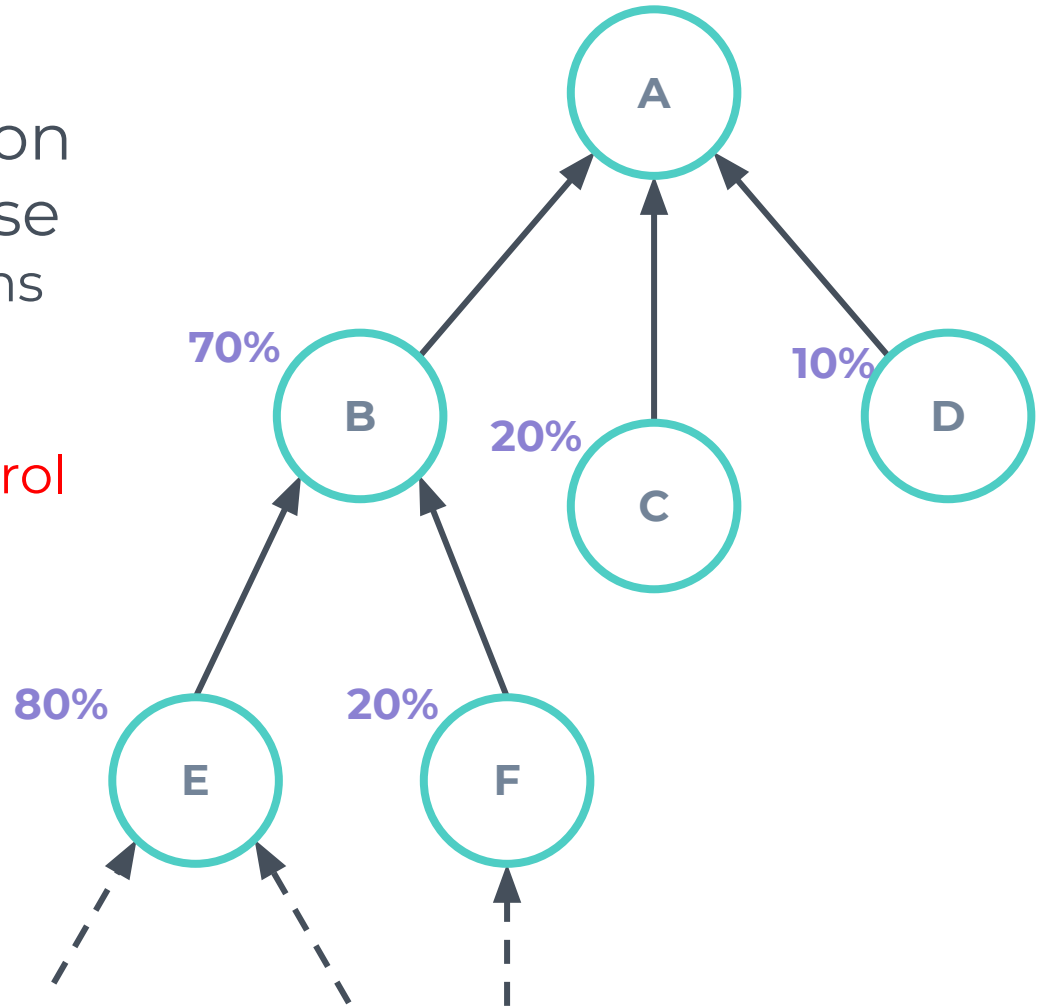
μ Matrix Hierarchical Address allocation

1. Tree data collection
 - a. μ Matrix relies on an underlying data collection routing protocol
 - i. Ex: RPL or CTP
 - b. It takes $O(n)$ control messages



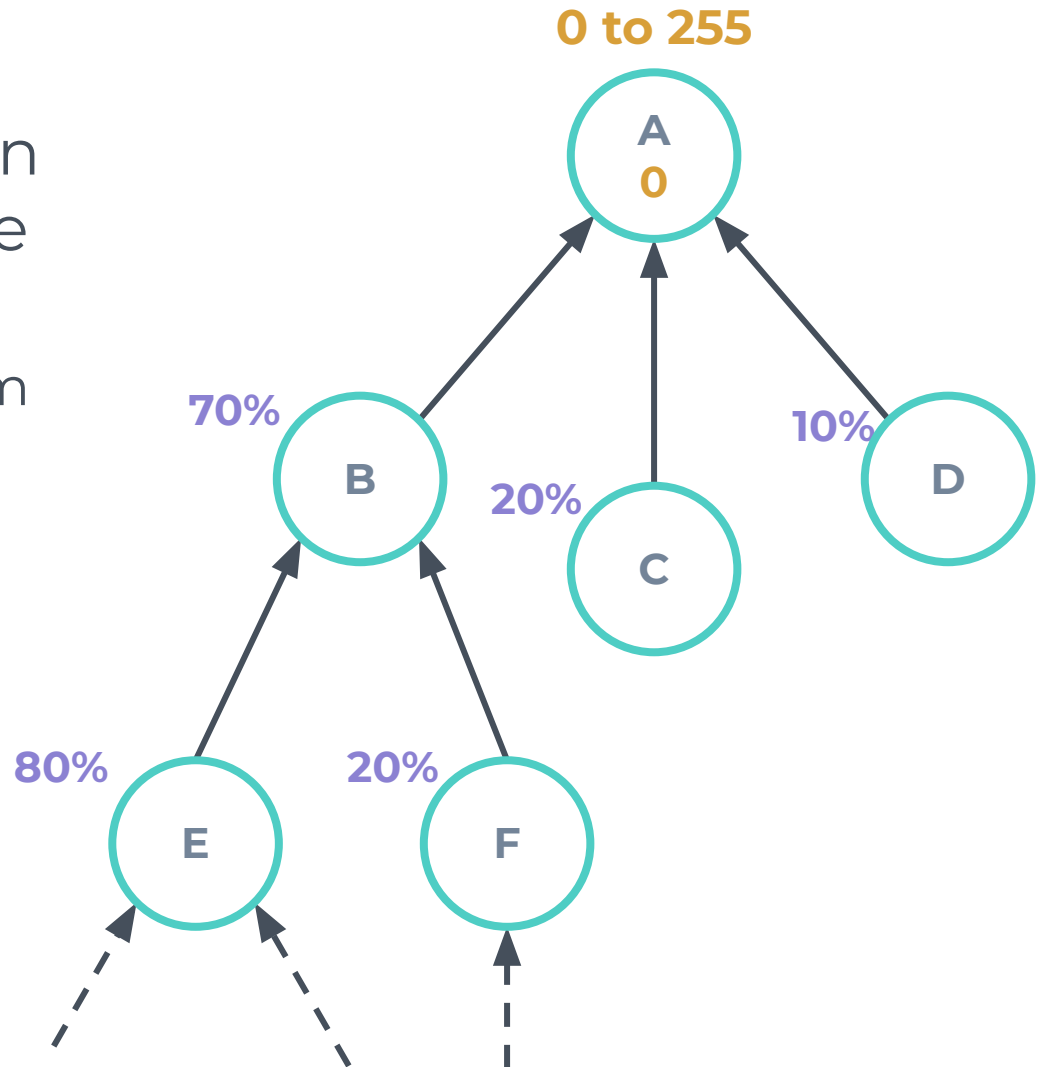
μMatrix Hierarchical Address allocation

1. Tree data collection
2. Aggregation phase
 - a. Each node informs the number of children
 - b. It takes $O(n)$ control messages



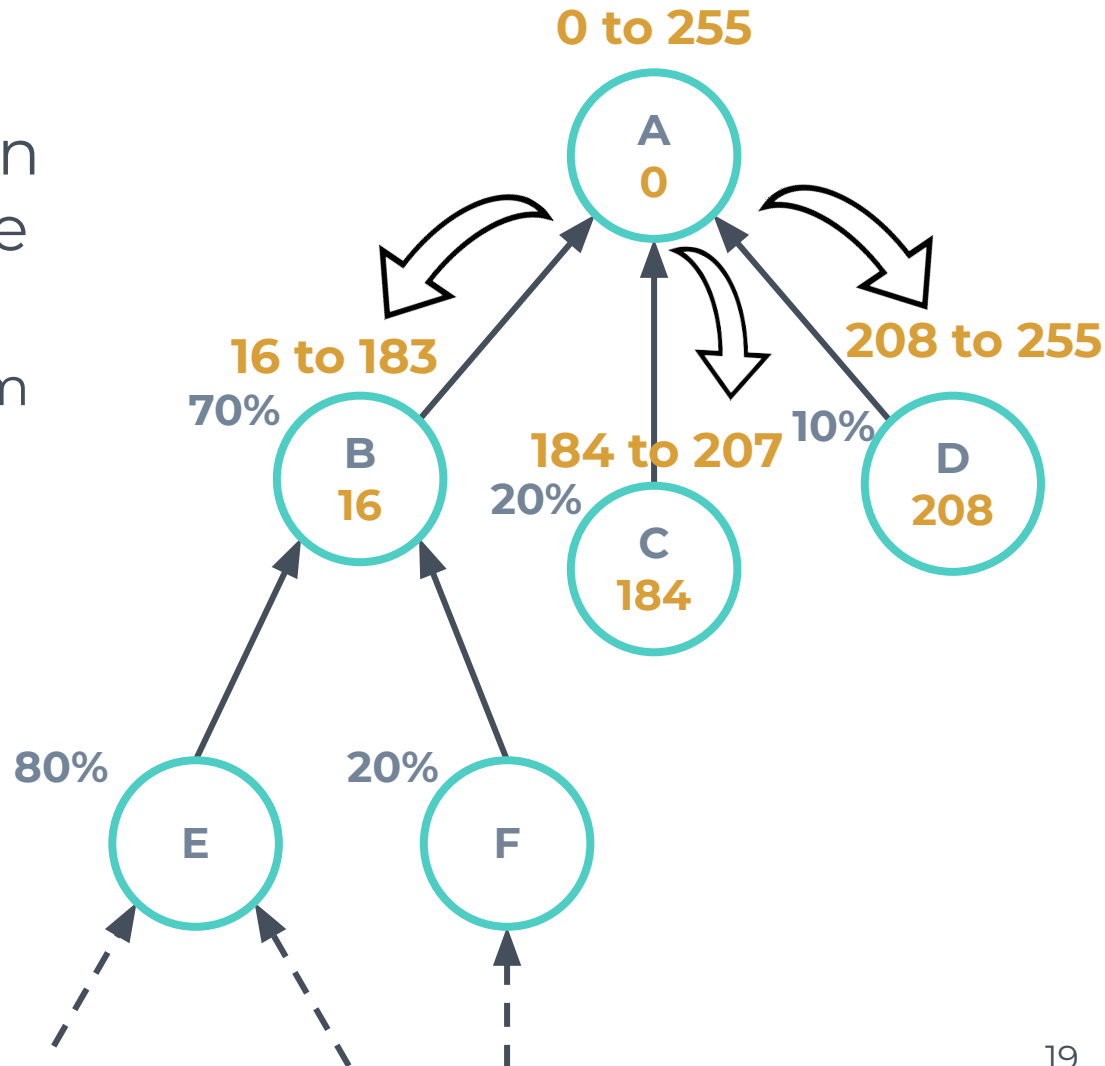
μMatrix Hierarchical Address allocation

1. Tree data collection
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3. Address allocation
 - a. Node receives from parent a range of available IPs proportionally
 - b. Nodes take one IP



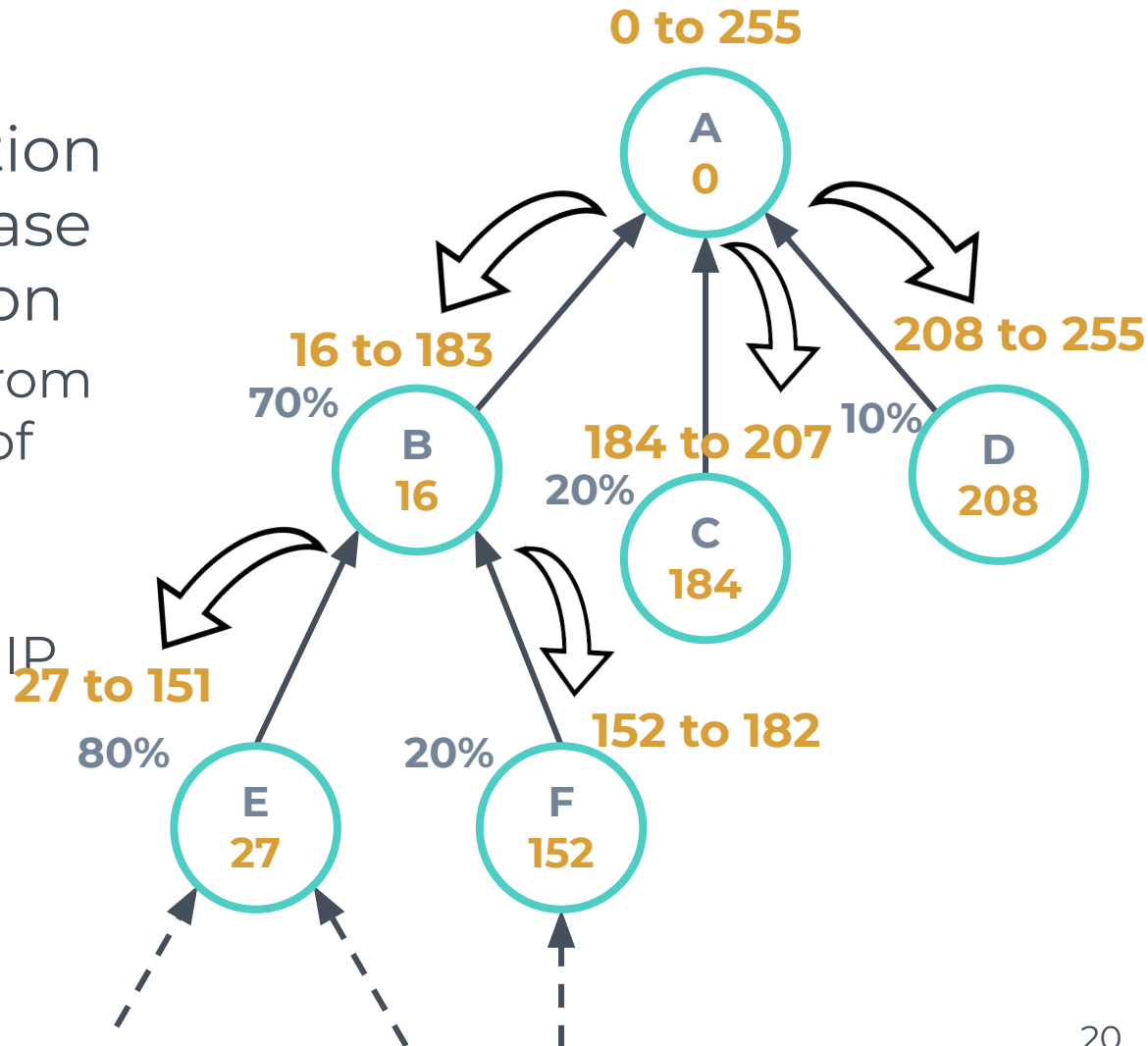
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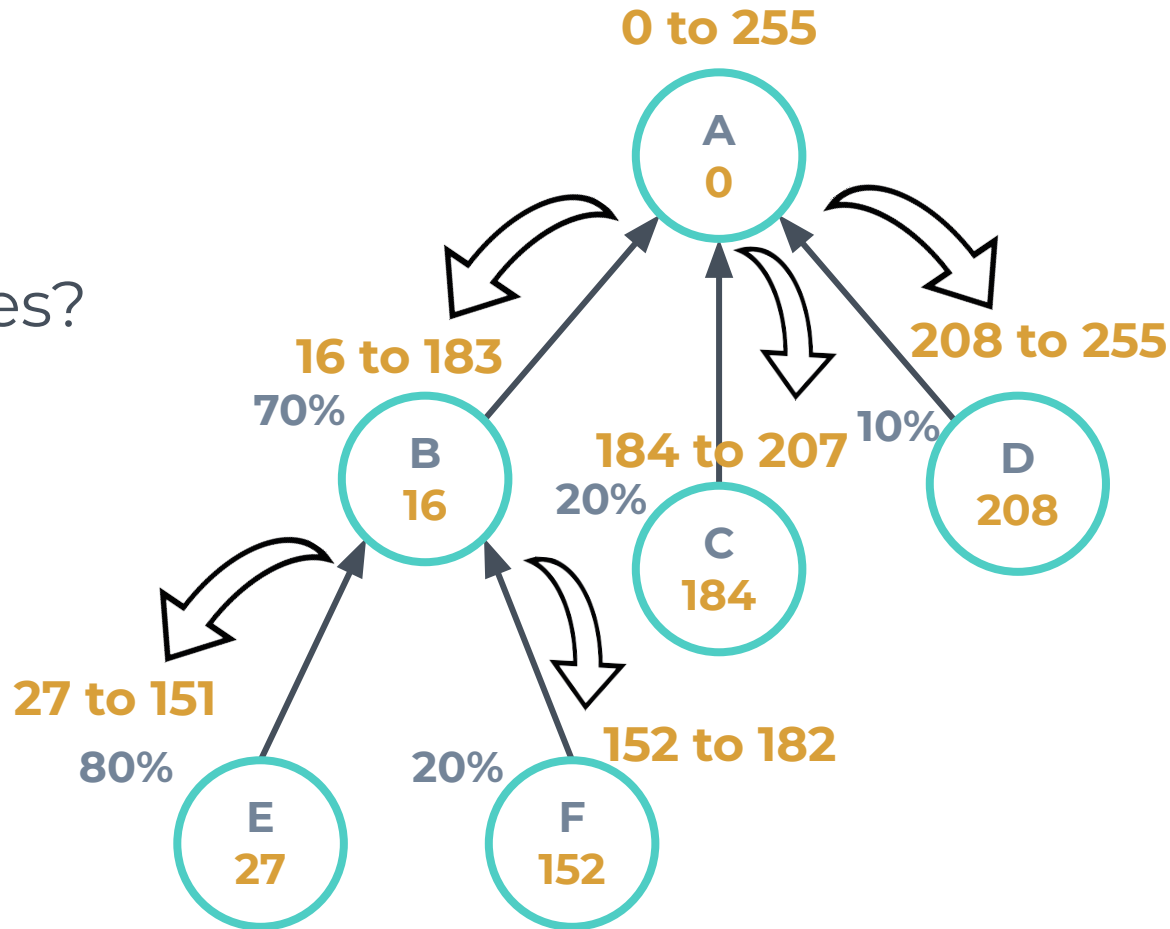
μMatrix Hierarchical Address allocation

1. Tree data collection
2. Aggregation phase
3. Address allocation
 - a. Node receives from parent a range of available IPs proportionally
 - b. Nodes take one IP
 - c. Recursively distribute the remaining IPs



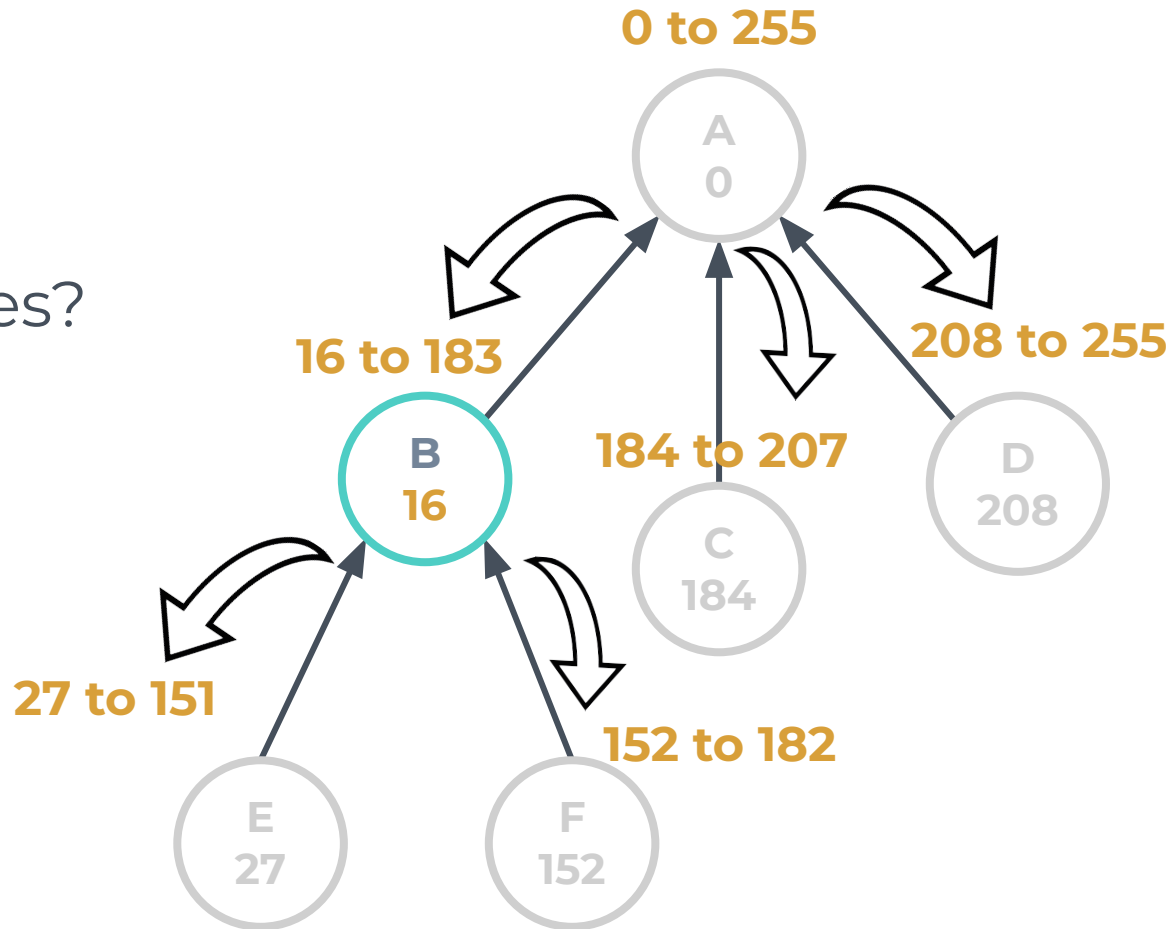
μMatrix Mobility management

1. What to do if B moves and the topology changes?



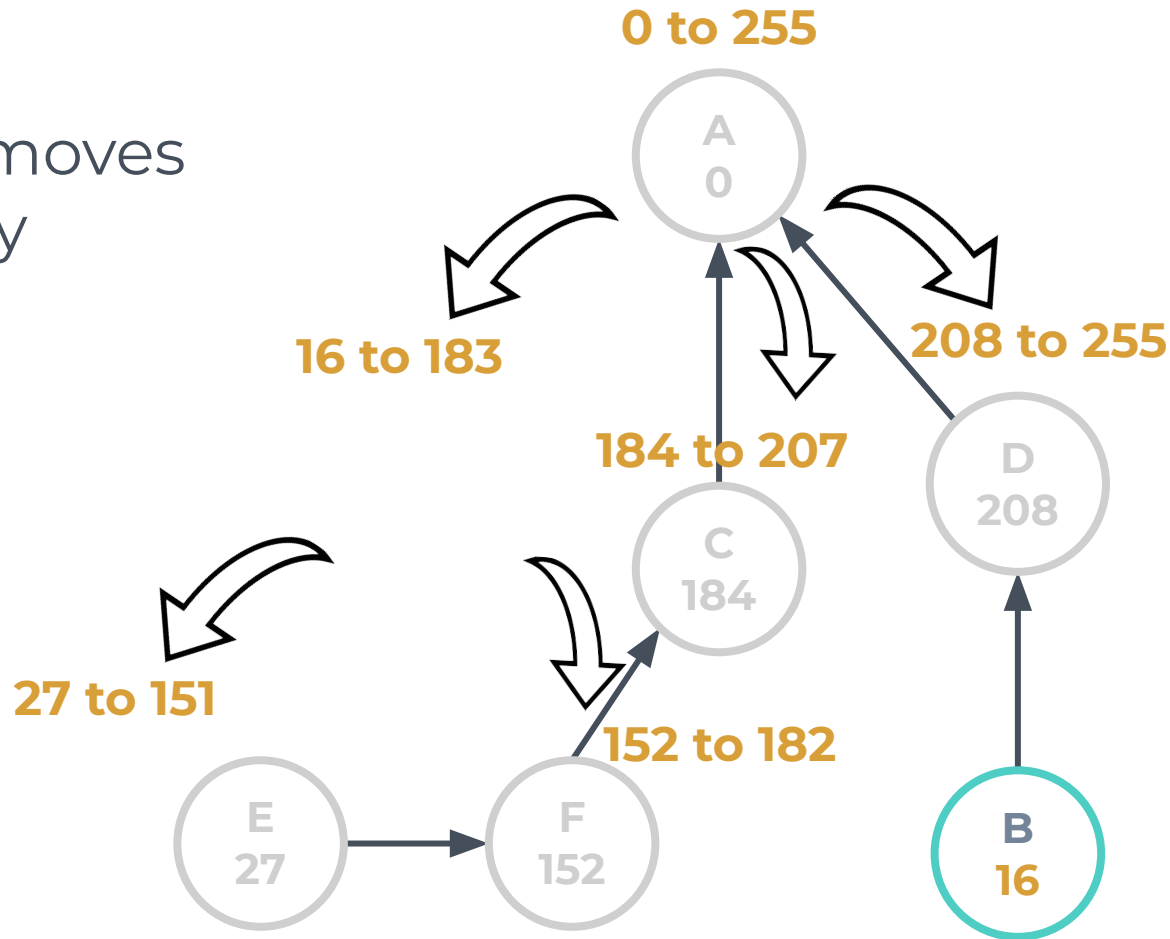
μMatrix Mobility management

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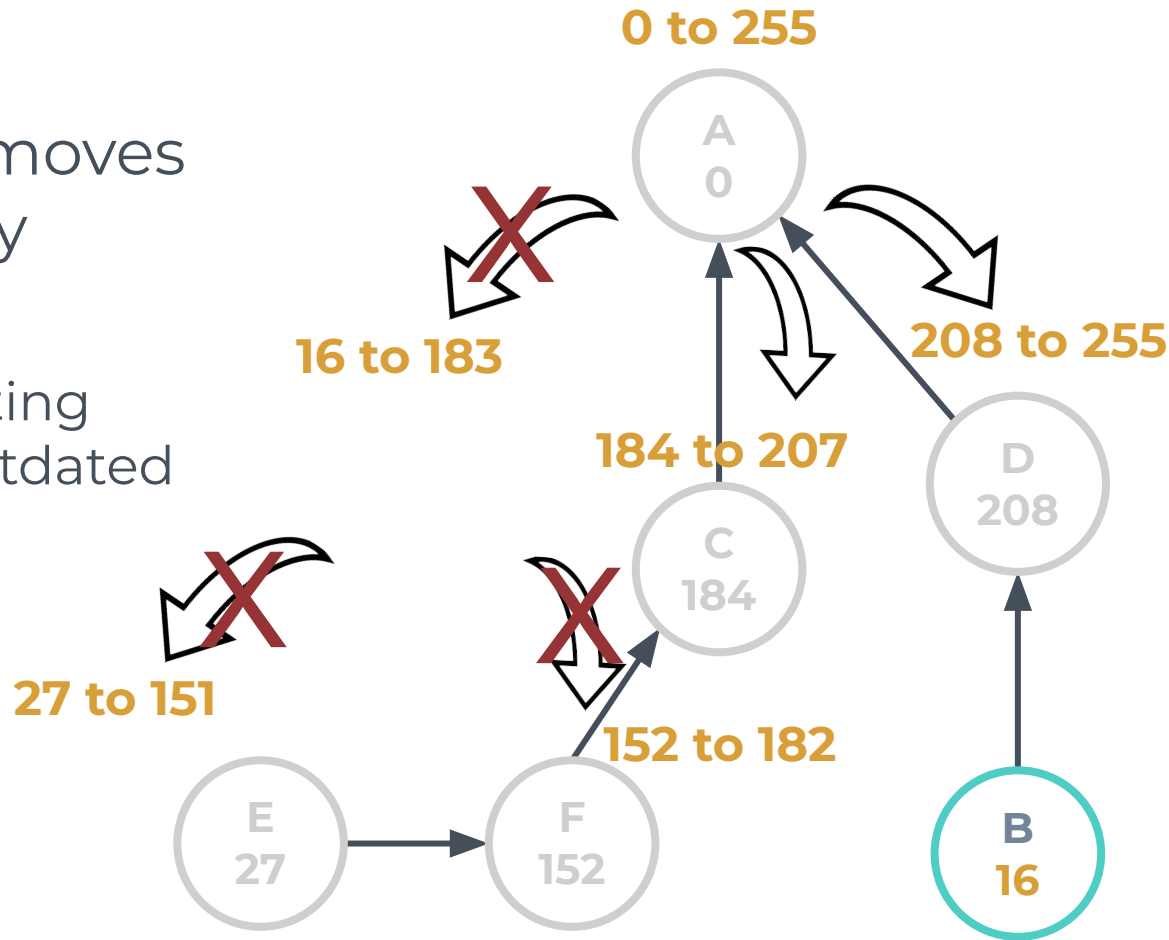
μMatrix Mobility management

1. What to do if B moves and the topology changes?



μMatrix Mobility management

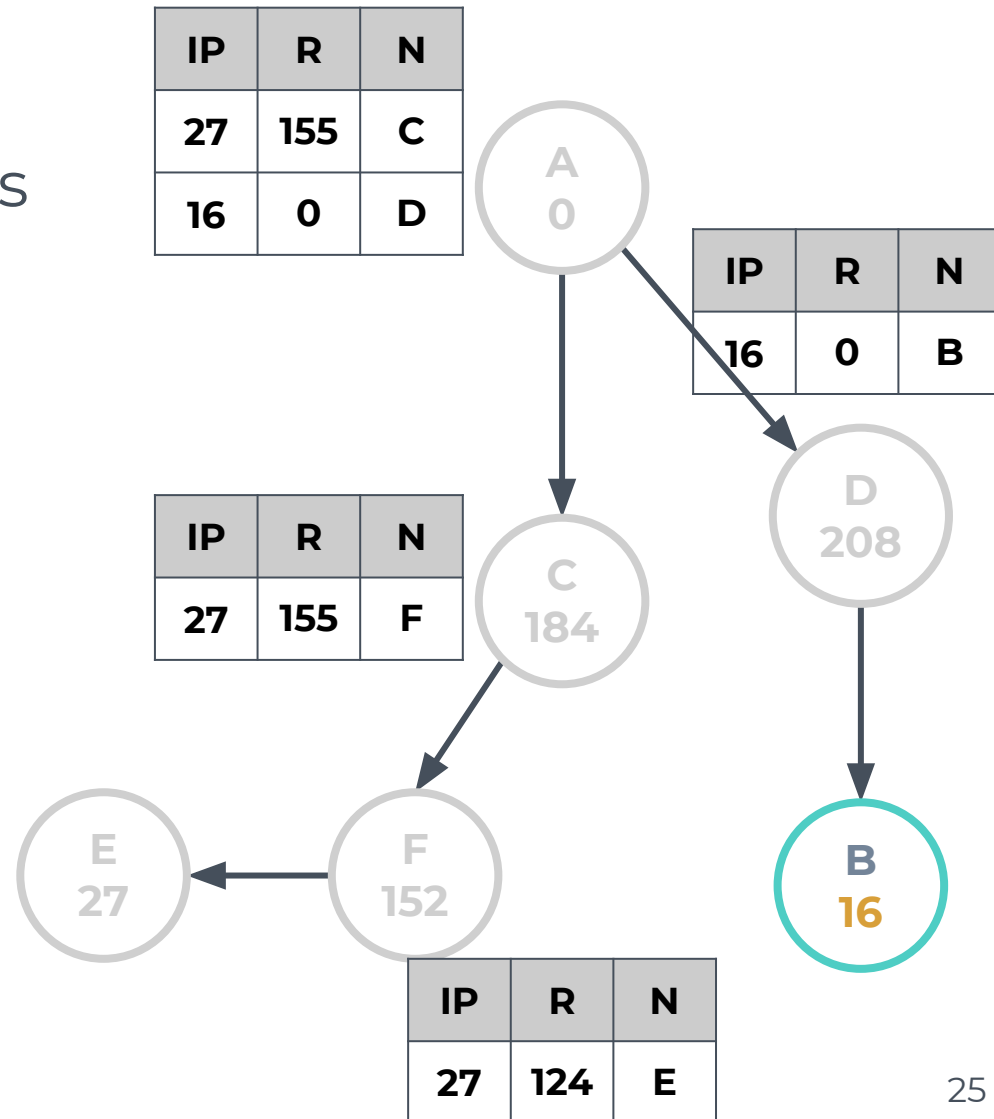
- 1. What to do if B moves and the topology changes?
 - a. The reverse routing tree become outdated



μMatrix Mobility management

1. What to do if B moves and the topology changes?

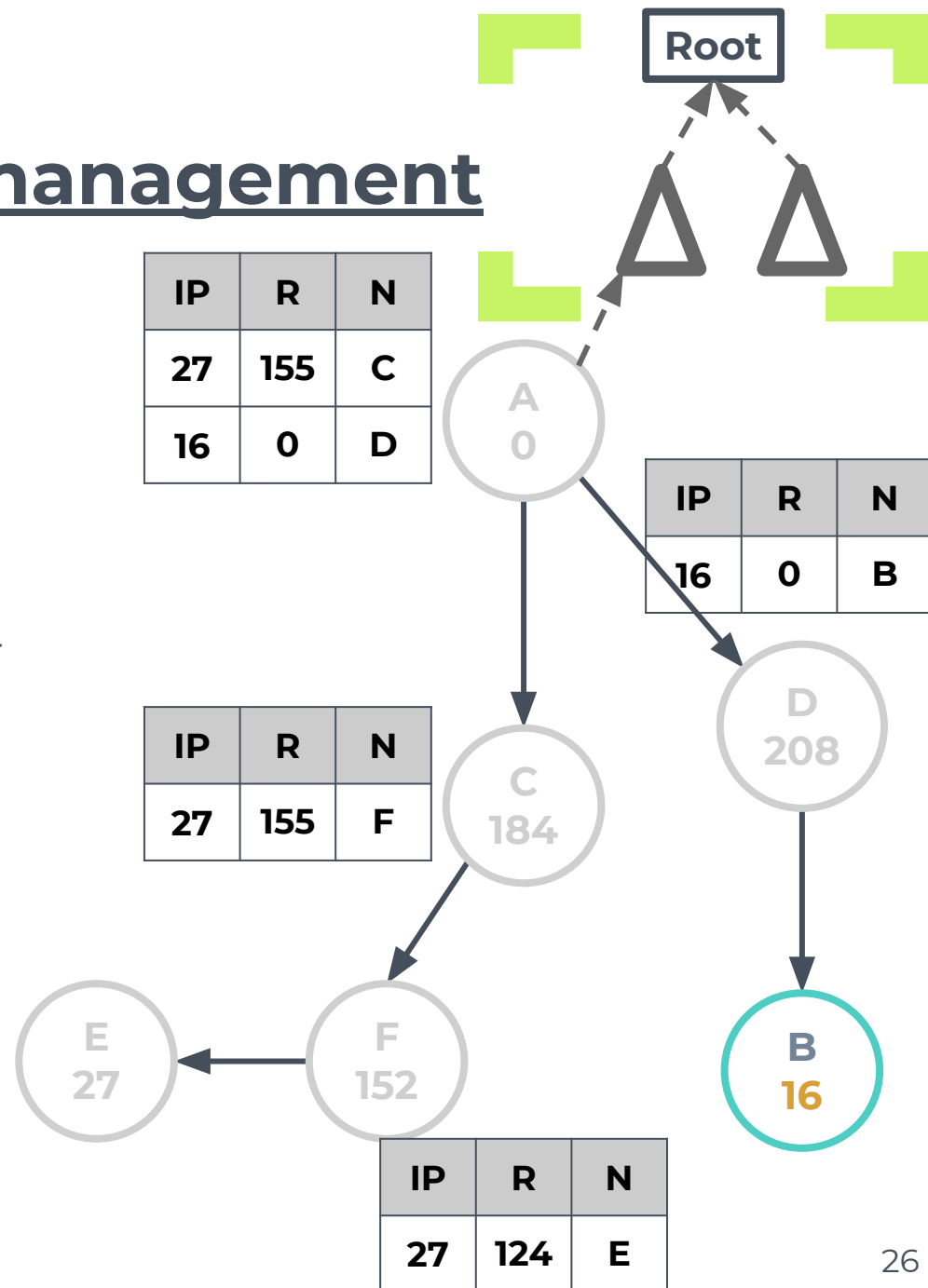
- **μMatrix Mobile engine redo the paths**



Design Overview

μMatrix Mobility management

- Local table updates
 - Nodes
 - From B to A
 - A is the Least Common Ancestor (LCA) of B
 - From E/F to A



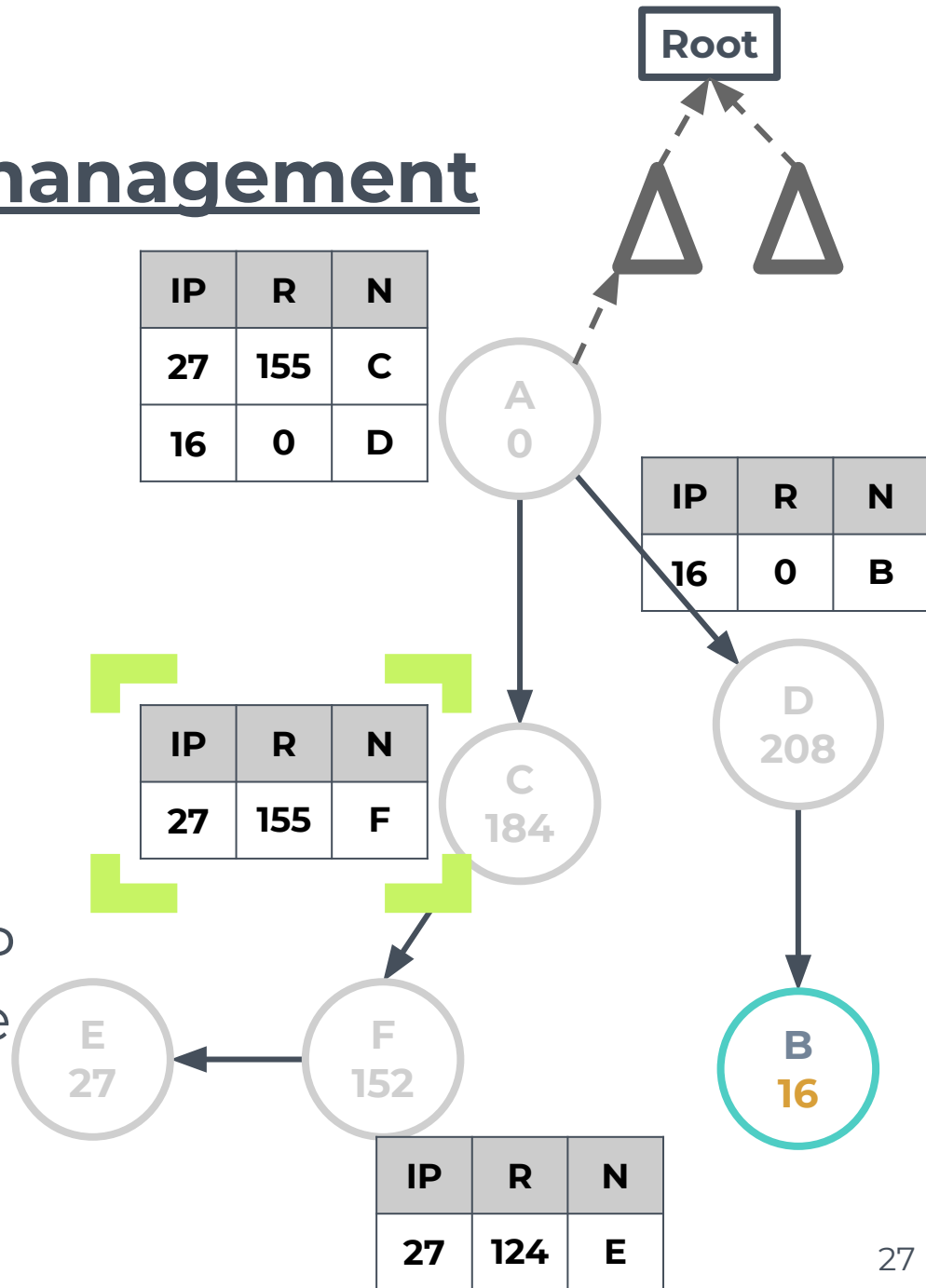
μMatrix Mobility management

- Local table updates

 - Nodes

 - From B to A
 - A is the Least Common Ancestor (LCA) of B
 - From E/F to A

- We only need **1 entry** IP for contiguous IP range (E and F)

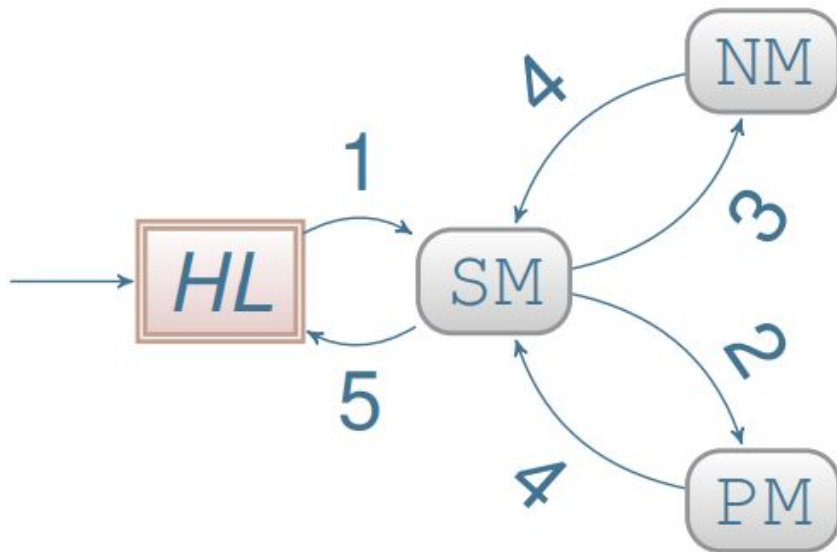


3.

Handling Mobility

1. State machine
2. Mobility detection
3. Handle node mobility

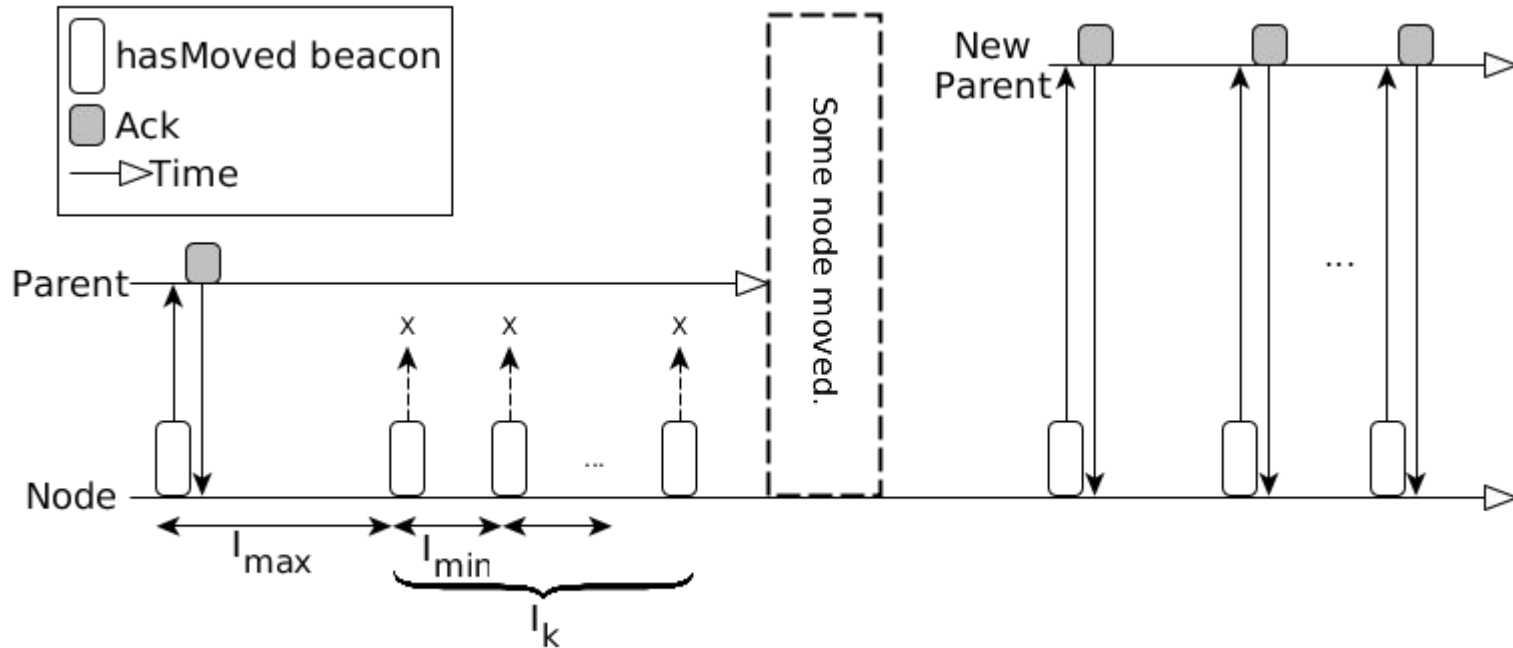
μMatrix Mobile engine - State Machine



HL	Home Location
SM	Someone Moved
NM	Node Moves
PM	Parent Moves

1	IPparent does not answer
2	Children are active
3	Children are NOT active
4	CTparent does not answer
5	IPparent is back

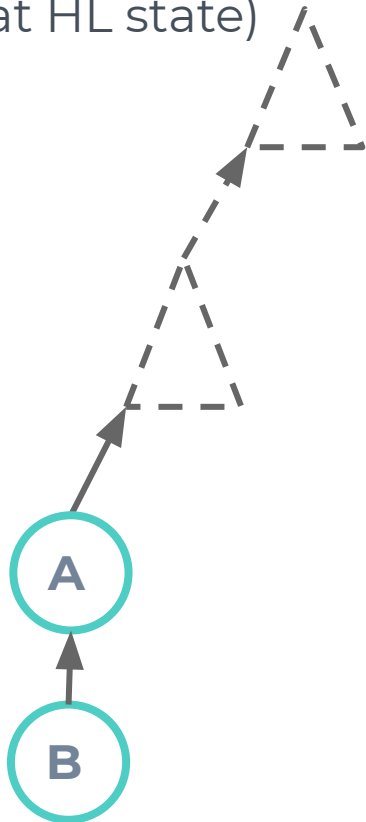
μ Matrix Mobile engine - Mobility detection



μMatrix Mobile engine - Leaf node moves

Static situation

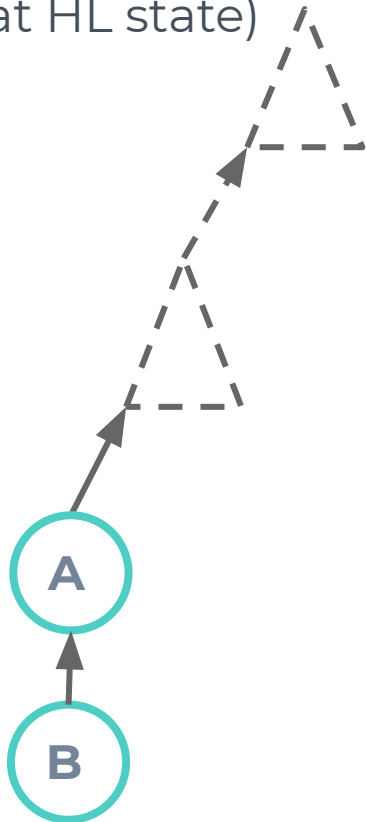
(nodes at HL state)



μMatrix Mobile engine - Leaf node moves

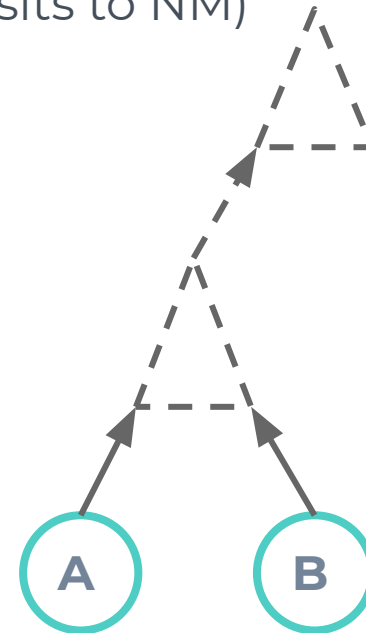
Static situation

(nodes at HL state)



B moves

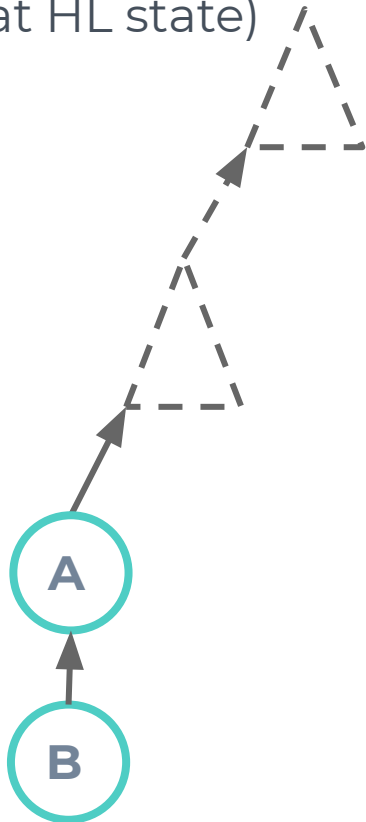
(B transits to NM)



μMatrix Mobile engine - Leaf node moves

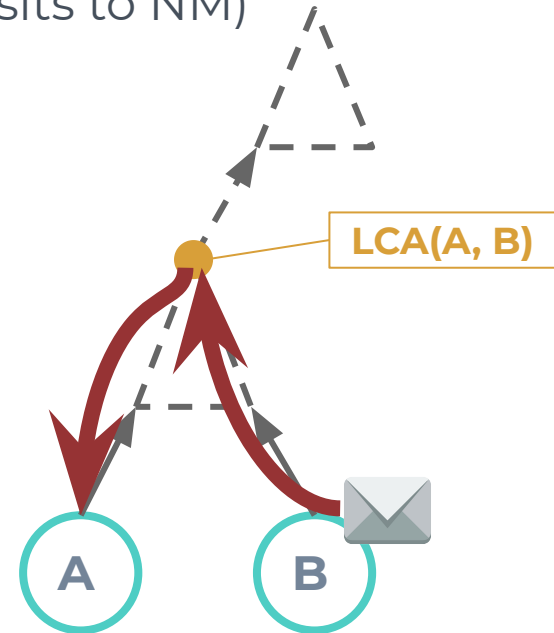
Static situation

(nodes at HL state)



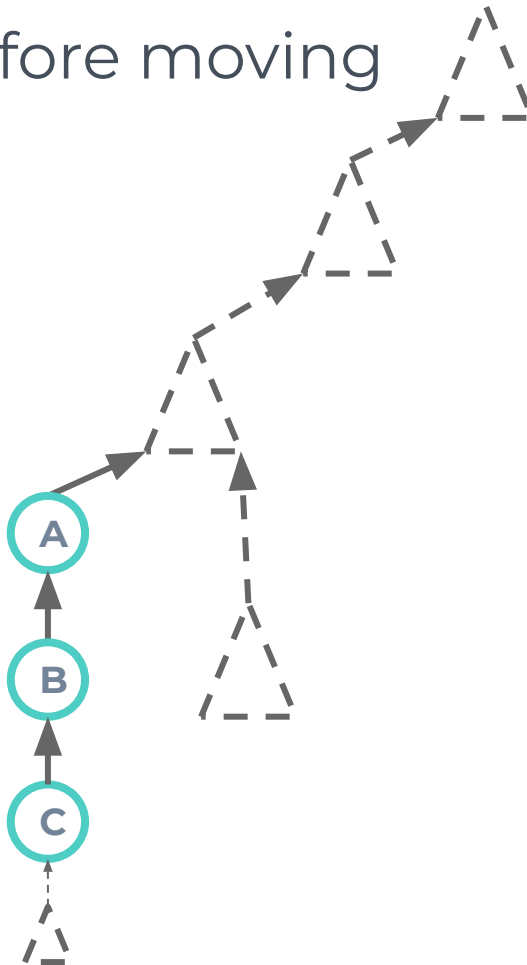
B moves

(B transits to NM)



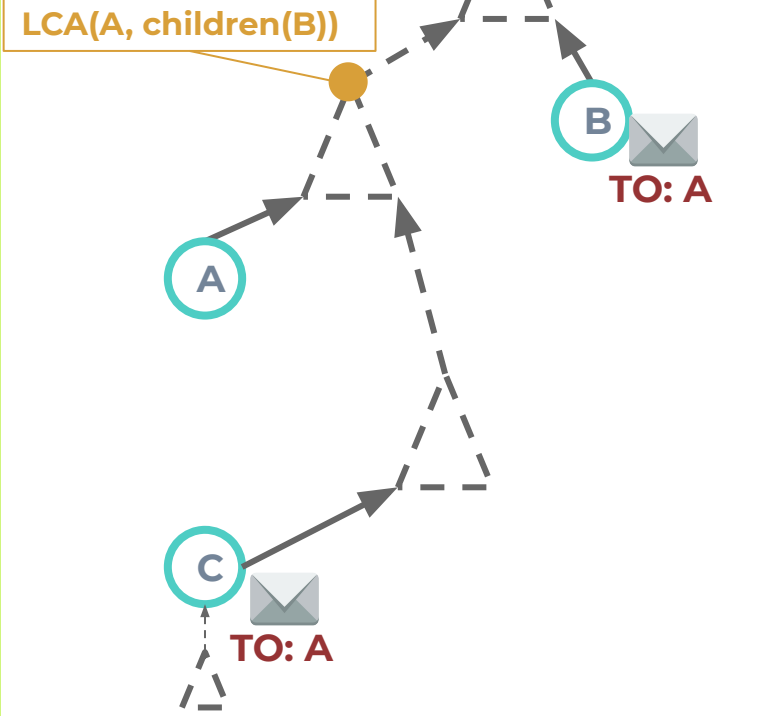
μMatrix Mobile engine - Non-Leaf node moves

B before moving



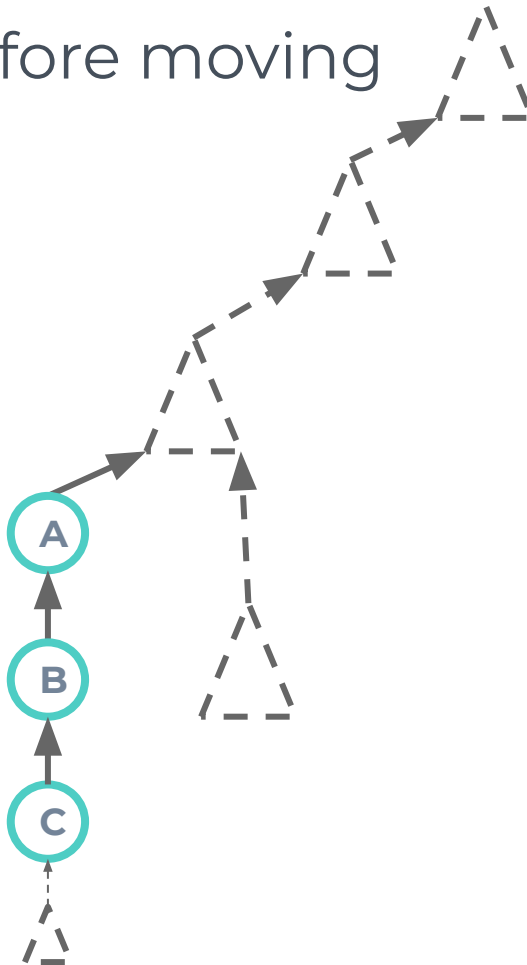
B after moving

(B transits to NM)
(C transits to PM)



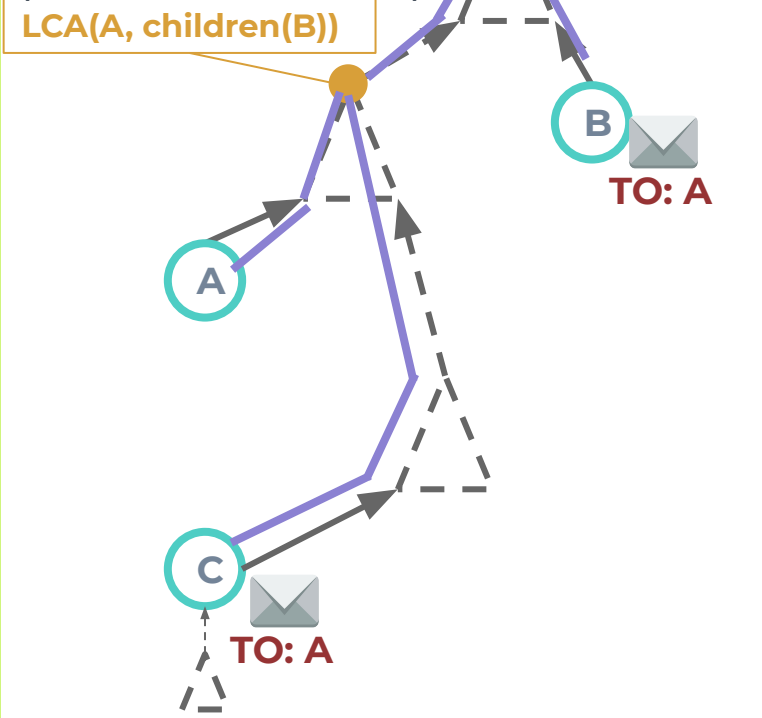
μMatrix Mobile engine - Non-Leaf node moves

B before moving



B after moving

(B transits to NM)
(C transits to PM)



4.

Complexity Analysis

1. Memory
2. Control messages

Complexity analysis

- The memory footprint to manage the mobility of one node μ Matrix is

$$\mathcal{M}(u) = O(\text{depth}(Ctree))$$

Collection Tree

Complexity analysis

- The memory footprint to manage the mobility of one node μ Matrix is

$$\mathcal{M}(u) = O(\text{depth}(Ctree))$$

Collection Tree

- The control message complexity of μ Matrix to perform routing under mobility is

$$Msg(\mu Matrix) = Msg(\mu Matrix^{hM}) + Msg(\mu Matrix^{kR})$$

Mobility detection cost

Route rebuild cost

Complexity analysis

- The memory footprint to manage the mobility of one node μ Matrix is

$$\mathcal{M}(u) = O(\text{depth}(Ctree))$$

Collection Tree

- The control message complexity of μ Matrix to perform routing under mobility is

$$\text{Msg}(\mu\text{Matrix}(Ctree)) = O\left(\frac{m \times I_k}{I_{min}} + \frac{n}{I_{max}}\right) + O\left(\frac{m \times \Delta}{\delta} \text{depth}(Ctree)\right)$$

m, n - mobile and static nodes respectively,

Δ - time away from home location.

$I_{min}, I_{max}, I_k, \delta$ - Reverse trickle param.

5.

Experiments

1. Mobility model
2. Parameters
3. Results

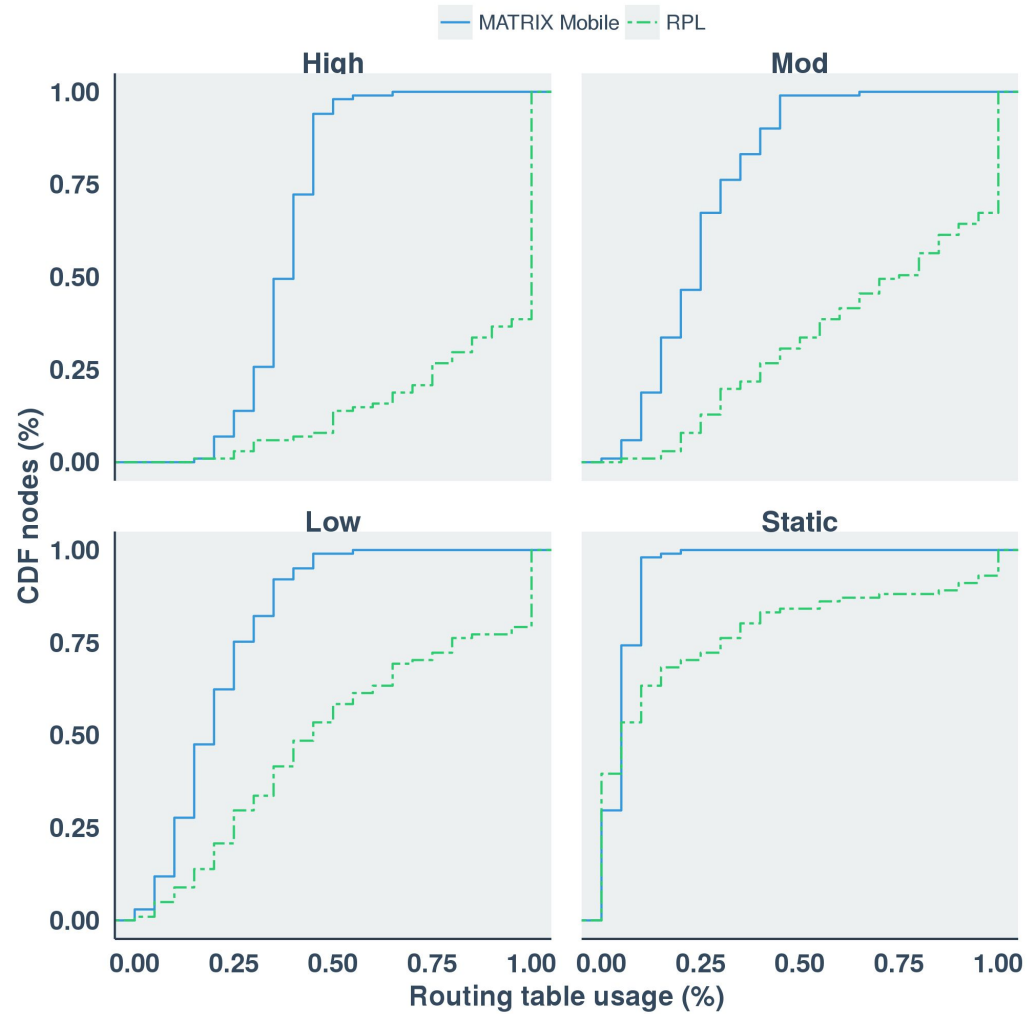
Cyclical Random Waypoint Mobility Model

1. Entities has an initial home position
2. Entities move to random destinations and speeds as in RWP
3. When an entity arrives at the destination, it stops for a given time T_{pause}
4. After n chosen destinations, the mobile entity returns to its initial position.

Simulation parameters

Parameter	Value		
	Low	Moderate	High
% mobile nodes	5%	10	15%
Node speed	Constant 4 m/s		
Tpause	Constant 300 s		
# nodes stop	Uniform Dist. in [1, 3] stops		
# nodes	101		
Application data packets	20 pks/node, 1 pkt/min		
Radio range	50m UDGGM constant loss		
Deployment area	400m x 400m		
Reverse Trickle Timer	I _{max} = 60s, I _{min} = 1s, I _k = 3		
RPL Trickle	I _{max} = 60s		
keepRoute beacon period	$\delta = 60s$		
Mtable (temporary table)	Size = 20 entries, TTL _{max} = 90s		

Results

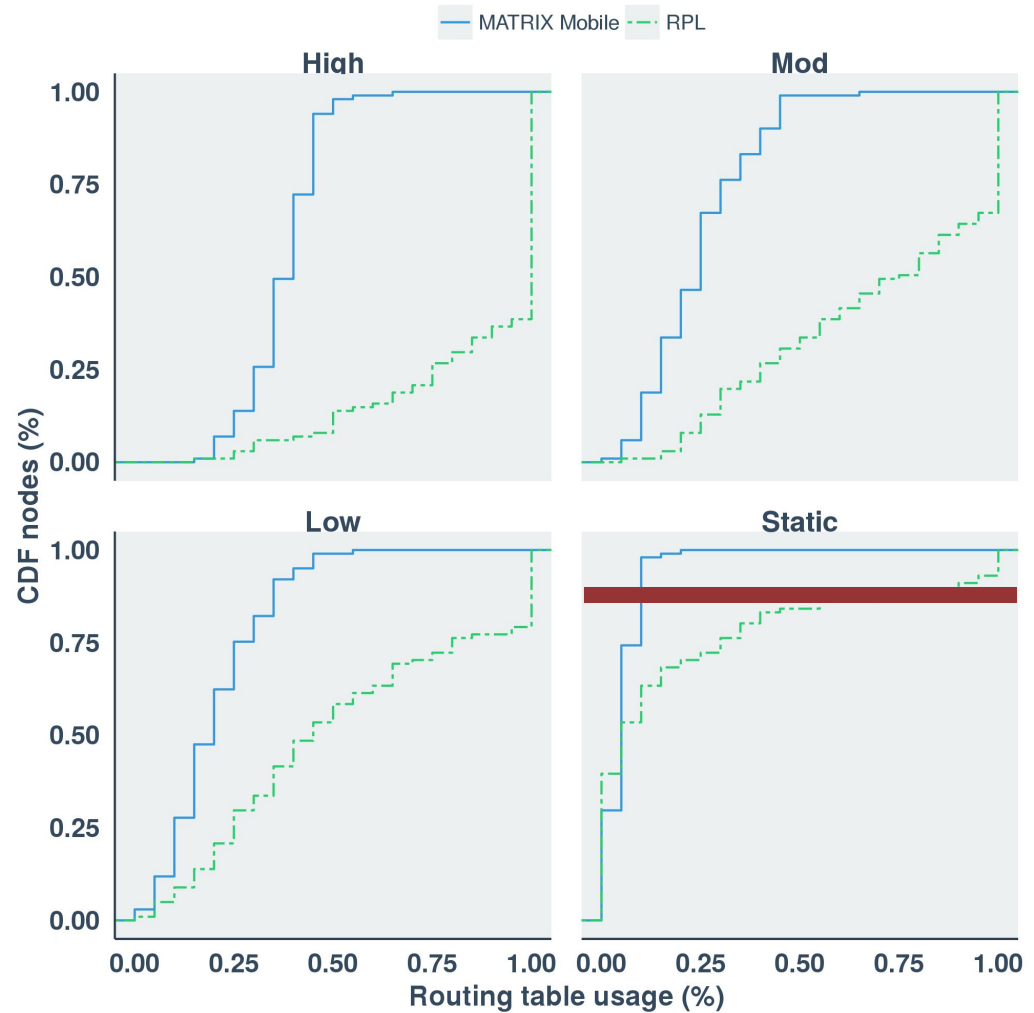


Results



For 85% of nodes

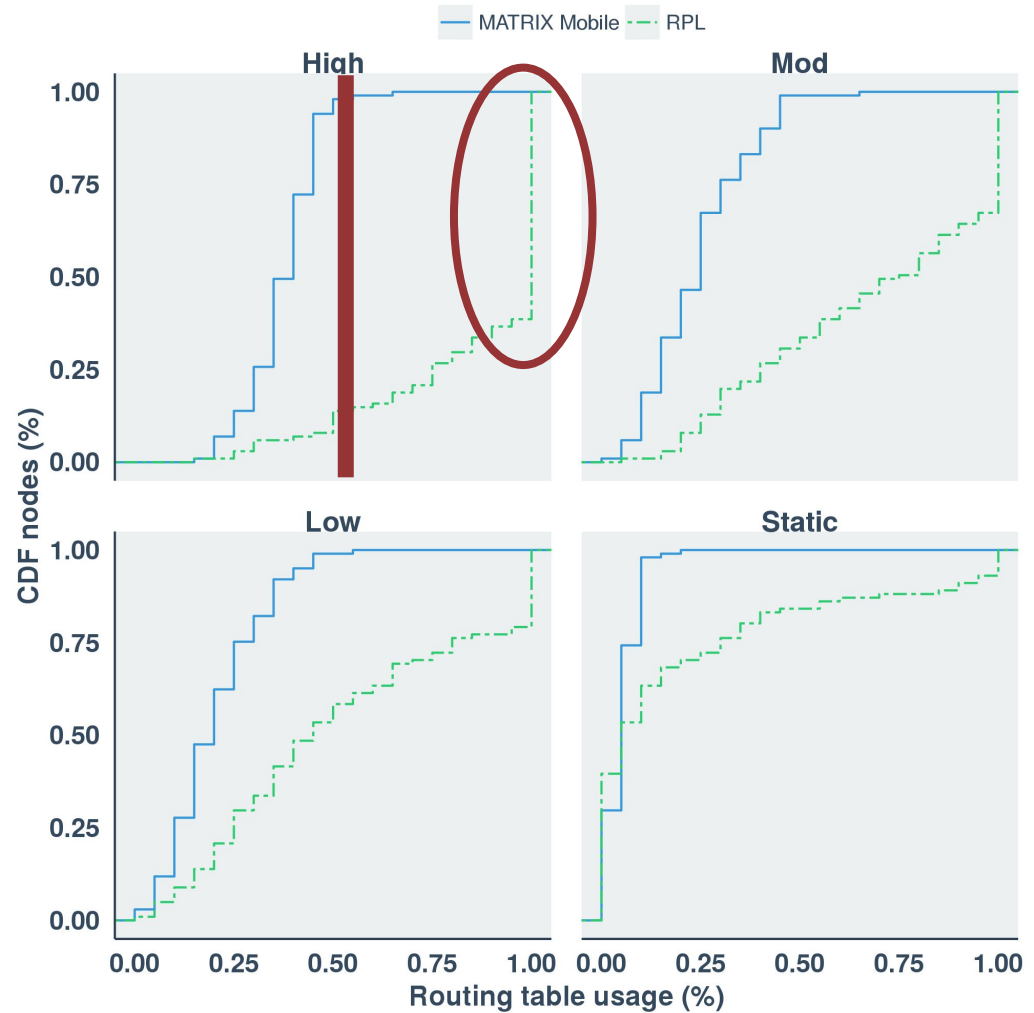
- RPL uses 55% of routing table,
- μ MATRIX only 15%



Results



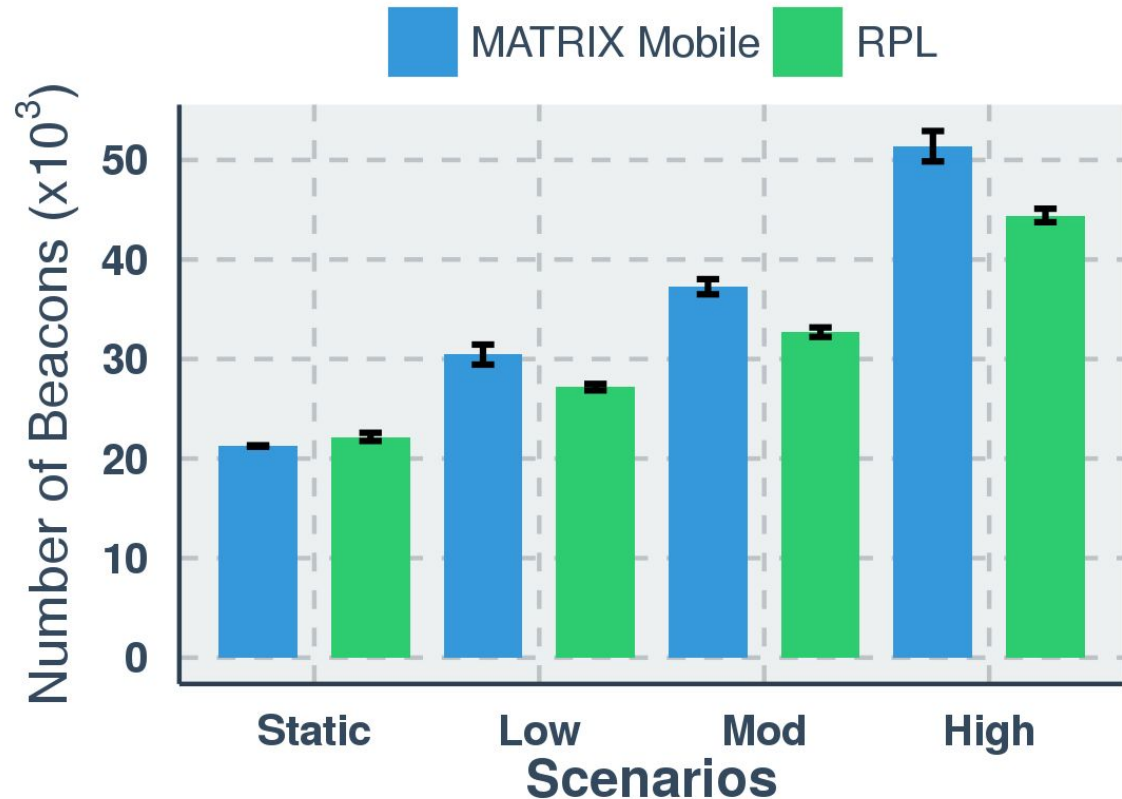
- μ Matrix requires 50% of available route entries
- RPL fails in routing due to full routing table



Results



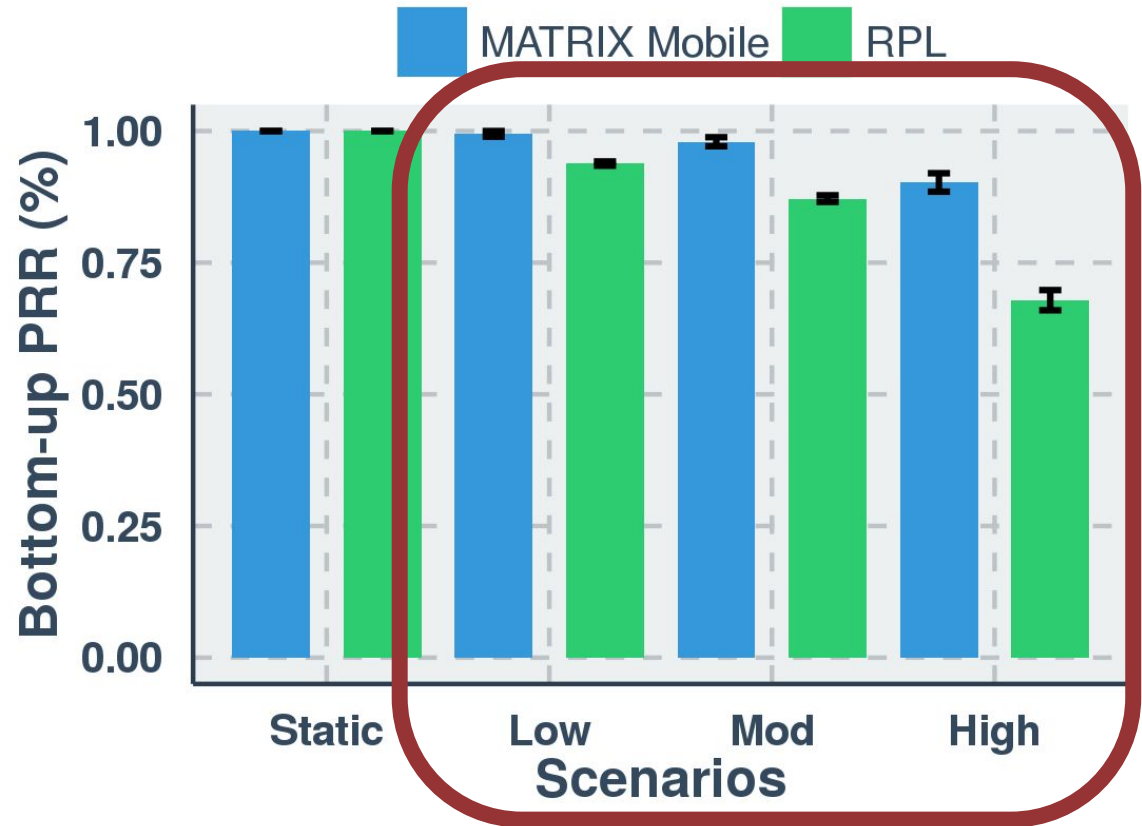
- RPL sends fewer control packets than μ Matrix
 - but the difference does not exceed 7.4%



Results



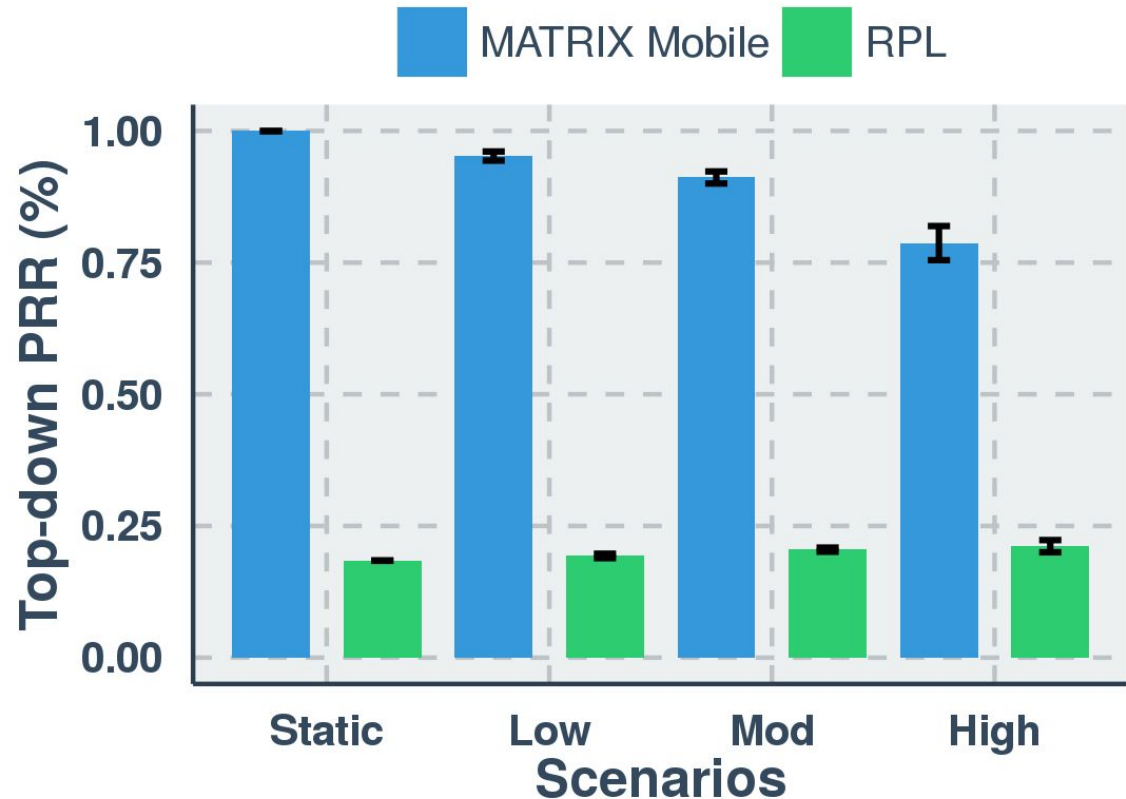
- μ Matrix detects mobility quickly, then it delivery more packets



Results



- μ Matrix 99.9% PRR in static scenario
- μ Matrix > 75% in high mobility scenario
- RPL suffers from poor reliability due a lack of memory



6.

Related work

Feature	μ Matrix	RPL	Co-RPL	MMRPL	ME-RPL	mRPL	DMR	Hydro	XCTP
Bottom-up	✓	✓	✓	✓	✓	✓	✓	✓	✓
Top-down	✓	✓	✓	✓	✓	✓		✓	✓
Any-to-any	✓	✓	✓	✓	✓	✓		✓	
Address Allocation	✓								
IPv6 support	✓	✓	✓	✓	✓	✓	✓		
Memory efficiency	✓								
Fault tolerance	✓								✓
Local Repair	✓								
Topological Changes	Reverse Trickle	Trickle	Periodic fixed	Reverse Trickle-like	Trickle	Trickle	Trickle	Periodic fixed	Trickle
Constraints	Eventually nodes return to home			Need static nodes	Need static nodes	Need static nodes	Need static nodes	Need static nodes	

Related work

7.

Conclusions

Final remarks

- ▣ We presented μ Matrix
 - ▣ An any-to-any routing protocol for 6LoWPAN
 - ▣ Allow mobile nodes
 - ▣ Hierarchical address allocation
 - ▣ Passive mobility detection
- ▣ We introduce CRWP
 - ▣ Suited for scenarios with cyclical movement patterns
- ▣ Future work
 - ▣ Extend experimental evaluation
 - Mobile models and traces

Thanks!

Any questions?

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Marcos A. M. Vieira, and Antonio A.F. Loureiro

{bruno.ps, olga, **lfvieira**, mmvieira, loureiro}@dcc.ufmg.br

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1.

Transition headline

Let's start with
the first set of
slides



Quotations are commonly printed as a means of inspiration and to invoke philosophical thoughts from the reader.

This is a slide title



- ▣ Here you have a list of items
- ▣ And some text
- ▣ But remember not to overload your slides with content

Your audience will listen to you or read the content, but won't do both.



Big concept

Bring the attention of your audience over a key concept using icons or illustrations

You can also split your content



White

Is the color of milk and fresh snow, the color produced by the combination of all the colors of the visible spectrum.

Black

Is the color of coal, ebony, and of outer space. It is the darkest color, the result of the absence of or complete absorption of light.

In two or three columns



Yellow

Is the color of gold, butter and ripe lemons. In the spectrum of visible light, yellow is found between green and orange.

Blue

Is the colour of the clear sky and the deep sea. It is located between violet and green on the optical spectrum.

Red

Is the color of blood, and because of this it has historically been associated with sacrifice, danger and courage.

A picture is worth a thousand words

A complex idea can be conveyed with just a single still image, namely making it possible to absorb large amounts of data quickly.





Want big impact?

Use big image.



Use charts to explain your ideas



And tables to compare data

	A	B	C
Yellow	10	20	7
Blue	30	15	10
Orange	5	24	16

Maps





89,526,124

Whoa! That's a big number,
aren't you proud?

89,526,124\$

That's a lot of money

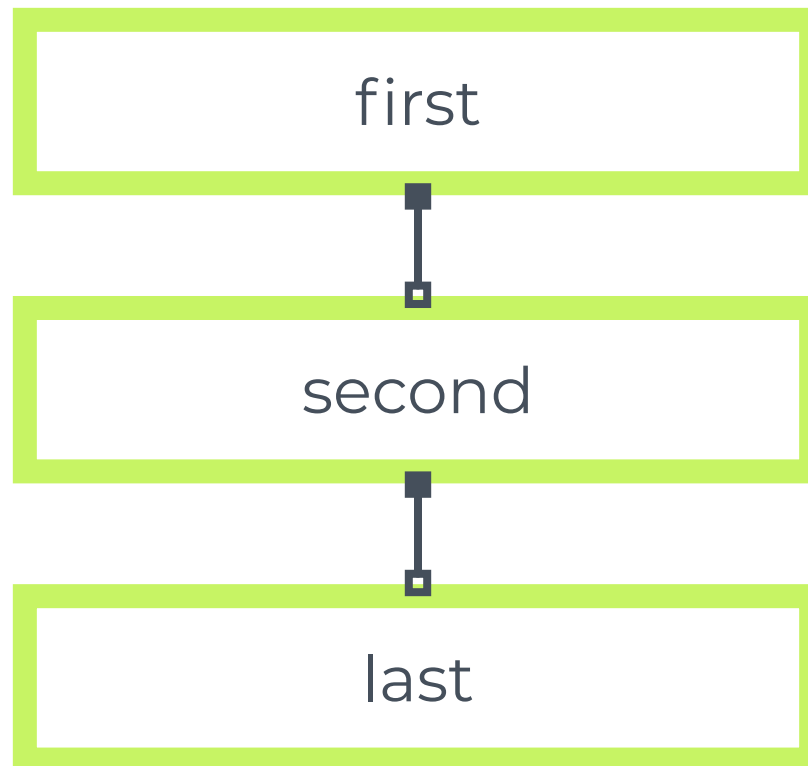
185,244 users

And a lot of users

100%

Total success!

Our process is easy



Let's review some concepts



Yellow

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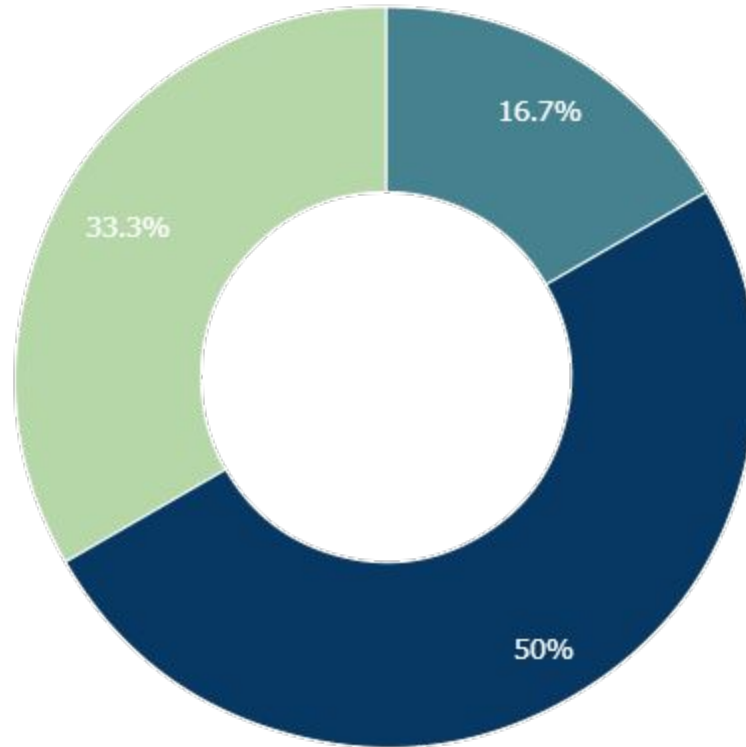
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■ A ■ B ■ C

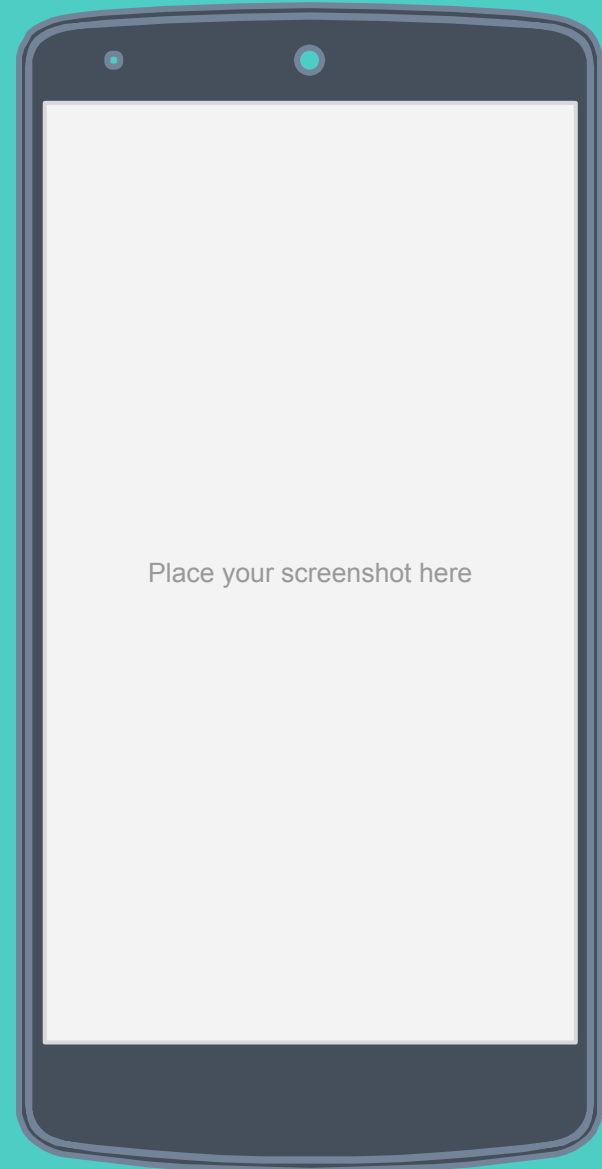


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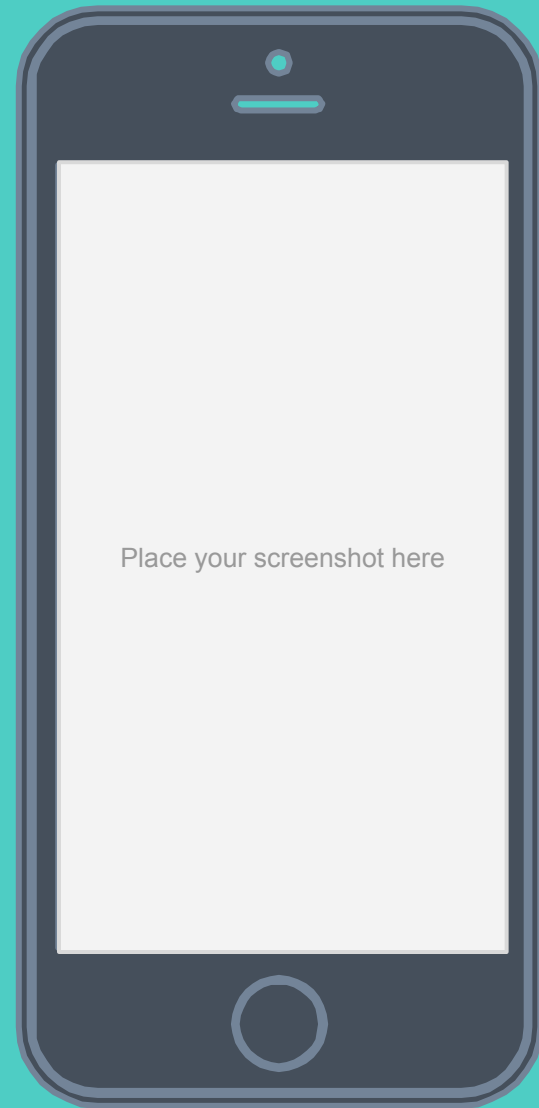
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iPhone project

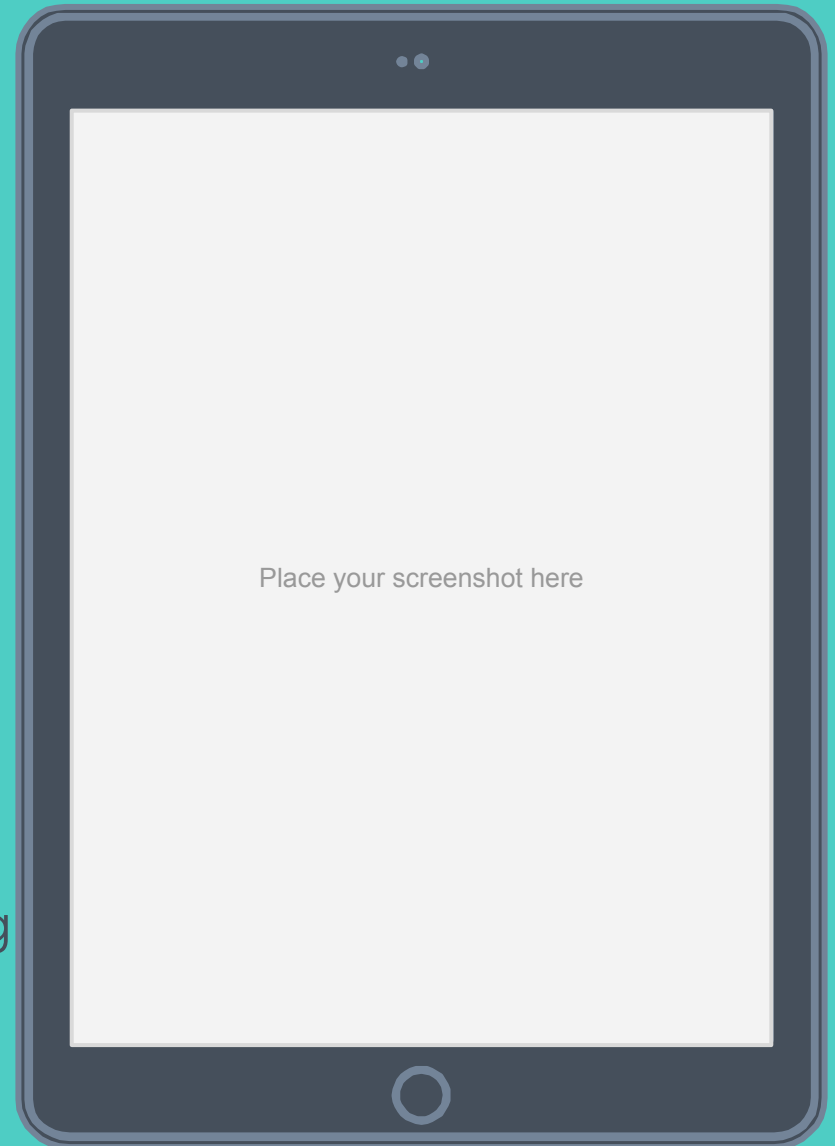
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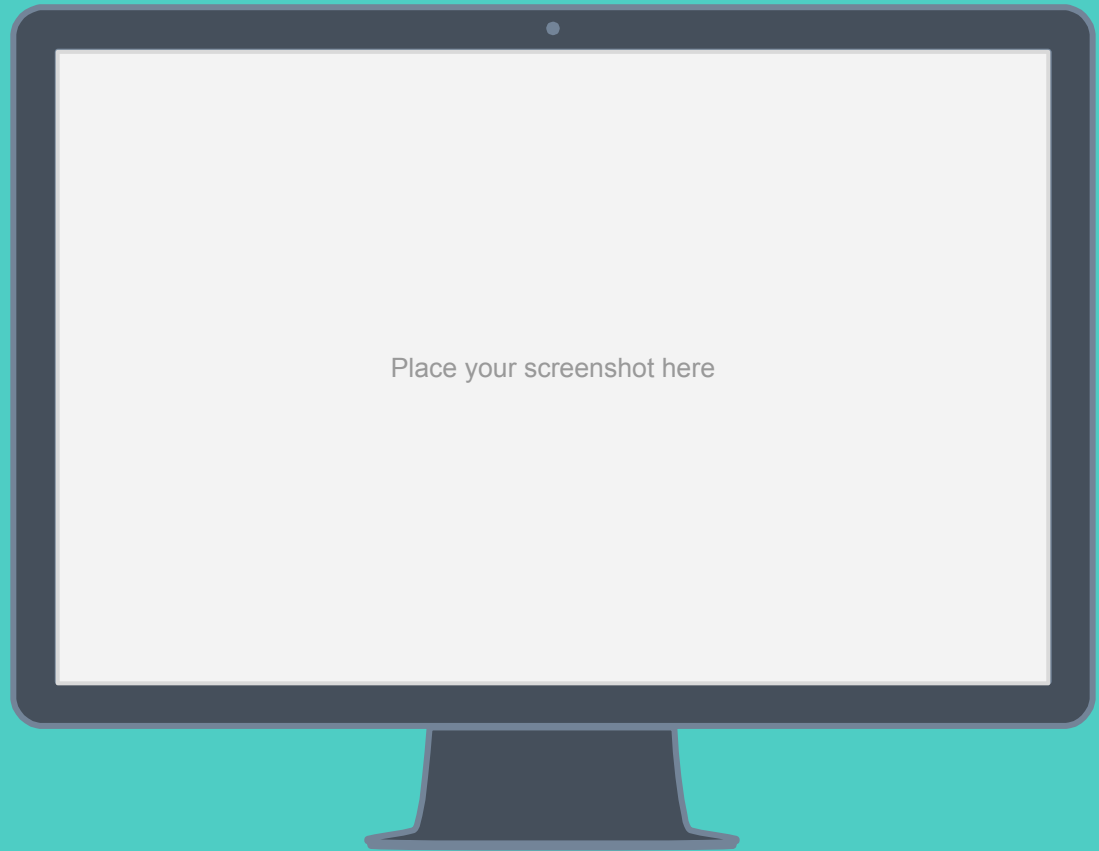




Tablet project

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Desktop project

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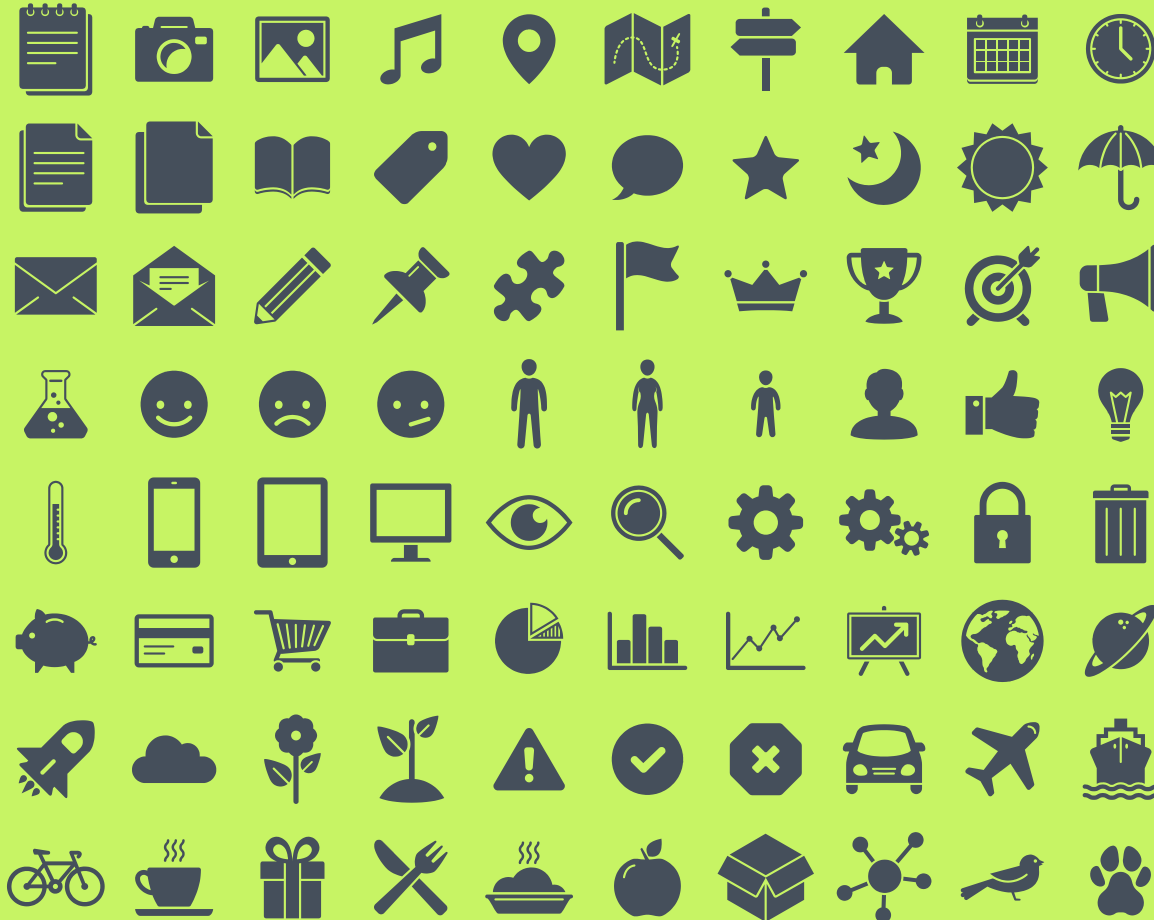
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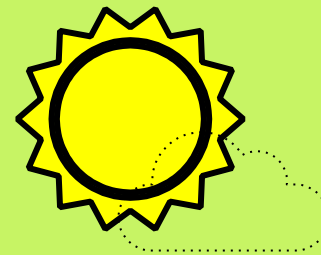
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